Homework1 – LTI systems, FT of DT signals

1. Determine whether the system has the following properties: stability, causality, linearity, time-invariance, memorylessness.

$$T(x[n]) = a \cdot x[n]$$

$$T(x[n]) = z[n] \cdot x[n], \ z[n] = (-1)^n$$

$$T(x[n]) = x[n - n_0]$$

$$T(x[n]) = ax[n] + b$$

$$T(x[n]) = ax[n] + bx[n - 3]$$

Present your reasoning!

2. For the systems from previous item that are LTI, calculate impulse responses and unit responses. Does it make sense to analyze impulse response of a system that is not LTI? (Why?)

3. An LTI system is described by its impulse response h[n]. For input x[n] it produces output y[n].

h[n] is nonzero only for $N_0 \le n \le N_1$ x[n] is nonzero only for $N_2 \le n \le N_3$

y[n] is nonzero only for $N_4 \le n \le N_5$

Express N_4 and N_5 in terms of N_0 , N_1 , N_2 , N_3 .

4. A DT signal x[n] was created by sampling a 6 kHz sine wave with 10 μ s sampling period. Find the normalized frequency, normalized angular frequency, period of x[n].

5. An LTI system has an impulse response h[n]. How can you calculate the step response k[n]? (k[n] is the response of the system when u[n] is at the input).

6. Let x[n] be a finite length sequence of length N. Let us define two sequences of length $N_2=2N$:

$$x_1(n) = \begin{cases} x(n) & 0 \le n \le N-1 \\ 0 & \text{otherwise} \end{cases}$$

$$x_2(n) = \begin{cases} x(n) & 0 \le n \le N - 1 \\ -x(n-N) & N \le n \le 2N - 1 \end{cases}$$

 X_1, X_2, X_3 denote DFT's of respective x's.

- How to compute X[k] from $X_1[k]$?
- How to compute $X_2[k]$ from $X_1[k]$?

7. Let x[n] be a periodic sequence with period N_1 . Thus x[n] is also periodic for period $N_3 = 3N_1$. We may compute $X_1[k] - N_1$ -point DFT of x[n] and $X_3[k] - N_3$ -point DFT of x[n].

- express X_3 in terms of X_1
- invent an example with $N_1 = 2$ and calculate X_1 and X_3 by hand.

8. x[n] – real, finite length sequence.

$$X(e^{j\omega}) = \mathcal{F}(x[n])$$

 $X[k] = DFT(x[n])$

$$\Im\{X[k]\} = 0$$

Prove or reject: $\Im\{X(e^{j\omega})\}=0$

(notation: 3 denotes imaginary part operator).

Hint: imagine two cases:

- (a) x[n] nonzero from 0 to L
- (b) x[n] nonzero from -L/2 to L/2 and symmetric around 0

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