EDISP (Z-transform) (English) Digital Signal Processing Z-Transform lecture

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z-transform

 \mathcal{Z} – a generalization of DTFT, similar to \mathcal{L} as a generalization of CTFT

$$X(z) = \sum_{n=-\infty}^{\infty} x(n) z^{-n}$$

 \longrightarrow DTFT is equal to X(z) at unit circle $z = e^{j\theta}$ **Convergence:** same as for DTFT of $x[n] \cdot r^{-n}$ (substitute $z = r \cdot e^{j\theta}$)

$$\sum_{n=-\infty}^{\infty} |x(n)r^{-n}| < \infty$$

example: u[n] is not absolutely summable; $u(n) \cdot r^{-n}$ can be, if $|r^{-1}| < 1$ $\longrightarrow \mathcal{Z}(u[n])$ is convergent for r > 1.

Properties:

- Linearity,
- shift $x(n-n_0) \stackrel{\mathbb{Z}}{\longleftrightarrow} z^{-n_0} \cdot X(z)$,
- multiplication $z_0^n \cdot x(n) \xleftarrow{\mathcal{Z}} X(z/z_0)$,
- transform differentiation $nx(n) \xleftarrow{\mathbb{Z}} -zdX(z)/dz$,

• conjugation
$$x^*(n) \xleftarrow{\mathbb{Z}} X^*(z^*)$$
,

- time reversal $x(-n) \xleftarrow{\mathcal{Z}} X(1/z)$,
- initial value x(0) = lim_{z→∞} X(z) if x(n) = 0 for n < 0 (hint: limit of each term ...)</p>
- ► multiplication $x_1(n) \cdot x_2(n) \xleftarrow{\mathbb{Z}} 1/(2\pi j) \oint_C X_1(v) X_2(z/v) v^{-1} dv$ complex! convolution

Examples

Inverse z - transform

$$x(n) = \frac{1}{2\pi j} \oint_C X(z) z^{n-1} dz$$

- ▶ Power series expansion (e.g for finite series) → "a series of deltas"
- Partial fraction expansion: X(z) a rational function with M zeros and N poles,

$$X(z) = \sum_{r=0}^{M-N} B_r \cdot z^{-r} + \sum_{k=1}^{N} \frac{A_k}{1 - d_k z^{-1}}, \quad A_k = (1 - d_k z^{-1}) \cdot X(z) \big|_{z = d_k}$$

Z-transform of a convolution

$$y[n] = x[n] * h[n] \longrightarrow y(n) = \sum_{k=-\infty}^{+\infty} x(k) \cdot h(n-k)$$

$$Y(z) = \sum_{n=-\infty}^{+\infty} \left[\sum_{k=-\infty}^{+\infty} x(k) \cdot h(n-k) \right] z^{-n} =$$

=
$$\sum_{k=-\infty}^{+\infty} \left[x(k) \sum_{n=-\infty}^{+\infty} h(n-k) z^{-n} \right] =$$

(we substitute $m = n - k$ so $n = k - m$)
=
$$\sum_{k=-\infty}^{+\infty} \left[x(k) \sum_{m=-\infty}^{+\infty} h(m) z^{-k-m} \right] =$$

=
$$\sum_{k=-\infty}^{+\infty} x(k) z^{-k} \sum_{m=-\infty}^{+\infty} h(m) z^{-m}$$

$$Y(z) = X(z) \cdot H(z)$$

And this is the main application of *z*-transform.

Z-transform and difference equations (1)

$$\sum_{k=0}^{N} a_{k} y(n-k) = \sum_{k=0}^{M} b_{k} x(n-k)$$

 $a_0 = 1$ traditionally

Simpler case of N = 0 (FIR, no recursion)

$$y(n) = \sum_{k=0}^{M} b_k x(n-k)$$

$$Y(z) = \sum_{k=0}^{M} b_k \mathcal{Z}[x(n-k)] =$$

$$= \sum_{k=0}^{M} b_k X(z) z^{-k} =$$

$$= X(z) \cdot \sum_{k=0}^{M} b_k z^{-k} =$$

$$= X(z) \cdot H(z)$$

Z-transform and difference equations (2)

Now the general case:

$$\sum_{k=0}^{N} a_{k} y(n-k) = \sum_{k=0}^{M} b_{k} x(n-k)$$
$$\sum_{k=0}^{N} a_{k} Y(z) z^{-k} = \sum_{k=0}^{M} b_{k} X(z) z^{-k}$$
$$Y(z) \sum_{k=0}^{N} a_{k} z^{-k} = X(z) \sum_{k=0}^{M} b_{k} z^{-k}$$
$$Y(z) = X(z) \cdot \frac{\sum_{k=0}^{M} b_{k} z^{-k}}{\sum_{k=0}^{N} a_{k} z^{-k}}$$

Recall that the transform is linear, and shift is represented by z - k operator.