Advanced RADAR techniques

- SAR + GMTI
- ISAR
- IfSAR (InSAR)
- GPR
- Noise radar
- Passive radar (coherent + radiometric) Secondary radars and similar systems:
- IFF
- AIS
- ILS



SAR image

SAR technique



SAR – angle & Doppler

•SAR – Earth surface mapping

- Doppler frequency changes with angle
- Low-pass filtering = unfocused SAR (one filter for all distances)
- Matched filtering = focused SAR (filter changes with distance!)

•STAP/GMTI – moving target detection with SAR

•SAR combined with Direction of Arrival = STAP (N antennas, 2D processing!) -> GMTI





- Inverse SAR
- imaging a moving (e.g. rotating) object: ship on waves, rotating satellite, aircraft in turn
 TIRA: 34m antenna for sattelite imaging



TIRA radar image of ADEOS with overlayed wiregrid model and the results of intrinsic motion and damage analysis

Should be like this...





IfSAR (InSAR) ex:SRTM mission

add third dimension to SAR Two antennas -> phase difference SRTM: 60m boom



Ground Penetrating Radar

- Check before you dig...
- De-mining

Technology:



- As LF as possible (penetration)
- ... as WB as possible (depth resolution)
- SAR (along-track resolution)
- ground bounce and multi-bounce problems

GPR image



Noise radar

- •Noise can fill wide band = good resolution
- •Pin-type autocorrelation function = low ambiguity
- Long integration time possible
- Good compatibility
- •Nonspecific signal = low probability of intercept
- (LPI) = covert operation
- Problems:
 - near-far echo
 - moving target (Doppler, stretch)
 - computational complexity

Daventry experiment (passive radar)



The BBC had a powerful short-wave transmitter Station near Daventry, the Empire Radio Station, with a power output of 10 kW. The wavelength was 49m and the continuous beam was about 30 degrees wide and with a 10 degree elevation.

Hadley Page Heyford bomber made a number of passes at differing altitudes from 6000 ft down to 1000 ft.



26th February, 1935 Arnold Wilkins (as operator), A.P.Rowe and Robert Watson Watt.

Two receiving aerials fed into a sensitive mobile receiver connected to an oscilloscope. The equipment had been rigged inside a van to detect any echoes that were bounced back from the aeroplane. After careful adjustment, the results were dramatic; 'blips' appeared on the screen at distances of up to eight miles.

Passive radar (coherent)

- •Uses audio/tv/cellular transmitters of opportunity
- Correlation receiver (two antennas)
- Problem with direct signal & near/far
- •Direction finding more receivers (or more transmitters)

Radiometric techniques (totally passive)

- Natural thermal emission of the scene (passive)
 Noise-like illuminator (active)
- •millimeter wavelengths (good resolution)
 - concealed weapon detection (CWD) even non-metallic objects (ceramic weapons and potentially plastic explosives) can be detected
 - detection of immigrants in soft-sided vehicles

DOA (ESM) systems

- Direction Of Arrival measuring objects own transmission
- locate emitters by triangulation (angles) or multilateration (TDoA – Time Difference of Arrival)
 --> multisite operation!
- •"Kolchuga" (UA), "Vera" (CZ)



IFF (SSR)

Identification Friend or Foe (mil.) or Secondary Surveillance Radar (civ.)

- To shoot or not to shoot?
- Who is it?
- Radar equation (1/R⁴) vs. (1/R²)
- Altitude measurement problem
- Technology: transponder, 2- channels
- 1030 MHz interrogation
- 1090 MHz reply

Required for all the aircrafts flying above some limit.



B-68. Interrogator krótkiego zasięgu zamontowany na przenośnej wyrzutni przeciwlotniczych pocisków rakietowych





IFF with prim. radar



IFF Modes

- •Mode 1: 64 codes, (mil ATC): type of aircraft or mission
- •Mode 2, (mil ATC) 4096 "tail numbers"
- •Mode 3/A (civ. ATC squawk code):
 - instrument flight rules unique A/C codes.
 - G/A A/C under visual flight rules common code 1200.
- •Mode C:aircraft altitude (usually alt.with 3/A)
 - special codes for emergency/hijack etc.
- •Mode S ("selective")
 - Duplex data link
 - More flight params sent down
- •ADS-B (Automatic Dependent Surveillance Broadcast) – reply w/o question

AIS

Automatic Identification System

- VHF (156-162 MHz)
- GPS/GLONASS position, course, maneuvering – every 2 to 10 s (underway), 3 min (anchor)
- various status info (cargo, destination) -
 - every 6 min
- more accuracy, more info than radar
- incl. safety-related messages



LOC Aerial

~1,000 ft

safe landing under bad visibility

Course

select knob

Course

deviation scale

90 Hz modulation depth • 108-112 MHz Localizer NAV warning Lubber line Compass flag flag Heading C select se bug рс NAV Dual TC 150 Hz glide-slope in pointers G de 90 Hz Symbolic SC aircraft He Glideslope **GS** Aerial se Course deviation bar (CDI) 50 : 150 Hz

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