

ESPTR
(English)

Signal Processing in Telecommunications and Radar

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ESPTR: General information

“Credits”	2h/week lecture + 2h/week project.																								
Lecture	Thursday, 08:15-10(Possible move to Tue, 08:15-10, probably room 162) Team: dr J. Misiurewicz, dr K. Kulpa, mgr M. Malanowski																								
Contact	J. Misiurewicz, (jmisiure@elka.pw.edu.pl) room 447. A web page is under construction (http://staff.elka.pw.edu.pl/~jmisiure/esptr)																								
Project	Simulation of a selected mechanism or technique. Three stages: definition, algorithm, program. Environment: Matlab or Octave, C/C++ (selected projects), other (special projects).																								
Tests	One test within lecture hours (see the schedule).																								
Exam	A final exam during the session																								
Scoring:	<table style="border-left: 1px solid black; border-right: 1px solid black; border-collapse: collapse; margin-left: 20px;"> <tr> <td style="padding: 2px 10px;">=</td> <td style="padding: 2px 10px;">10%</td> <td style="padding: 2px 10px;"></td> <td style="padding: 2px 10px;">test</td> </tr> <tr> <td style="padding: 2px 10px;"></td> <td style="padding: 2px 10px;"></td> <td style="padding: 2px 10px;">10%</td> <td style="padding: 2px 10px;">P1: definition</td> </tr> <tr> <td style="padding: 2px 10px;"></td> <td style="padding: 2px 10px;">+</td> <td style="padding: 2px 10px;">10%</td> <td style="padding: 2px 10px;">P2: algorithm</td> </tr> <tr> <td style="padding: 2px 10px;"></td> <td style="padding: 2px 10px;">+</td> <td style="padding: 2px 10px;">20%</td> <td style="padding: 2px 10px;">P3: program</td> </tr> <tr> <td style="padding: 2px 10px;">=</td> <td style="padding: 2px 10px;">40%</td> <td style="padding: 2px 10px;"></td> <td style="padding: 2px 10px;">Project total</td> </tr> <tr> <td style="padding: 2px 10px;">=</td> <td style="padding: 2px 10px;">50%</td> <td style="padding: 2px 10px;"></td> <td style="padding: 2px 10px;">exam</td> </tr> </table>	=	10%		test			10%	P1: definition		+	10%	P2: algorithm		+	20%	P3: program	=	40%		Project total	=	50%		exam
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Plan

- Some basics: frequency conversions, sampling&D/A, digital processing
 - Radio channel, propagation, software radio, directional reception
 - Radar basics, pulsed/CW radar, special radars
 - Digital broadcasting and reception: DAB, DVB
 - Cellular systems up to UMTS, structure, modulations, receivers
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Basics: sampling

- ideal sampling
 - non-ideal sampling: model as LP filter(conv)+sampling(mul), integrating AD converter case (multimeter)
 - Nyquist sampling
 - undersampling of narrowband signals (ideal and non-ideal case)
 - reconstruction (ideal and nonideal)
 - Oversampling to ease the antialiasing filter design
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The Sampling Theorem

Named also after:

- 1915 Edmund T. Whittaker (UK)
- 1928 Harry Nyquist [ny:kvist] (SE)
- 1928 Karl Küpfmüller (DE)
- 1933 Vladimir A. Kotelnikov (USSR)
- 1946 Gábor Dénes (HU) → Dennis Gabor (US)
- 1949 Claude E. Shannon (US)
- Cardinal Theorem of Interpolation Theory

Nyquist frequency, Nyquist rate

Sampling: bandlimited signal (aliasing problem)

Moiré pattern - as seen on TV, an example of too low sampling frequency.

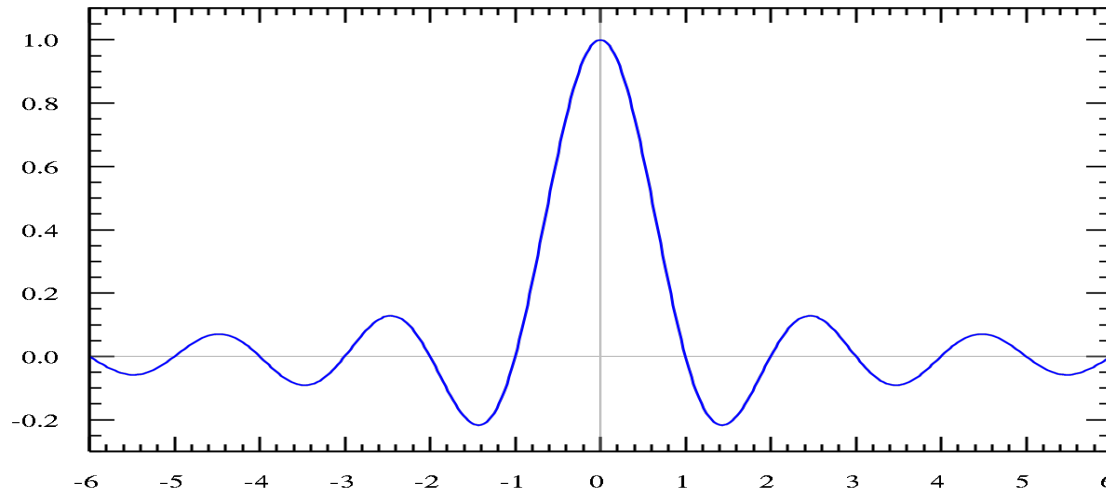
Reconstruction

Reconstruction: interpolation,

$$x(t) = \sum_{n=-\infty}^{\infty} x[n] \cdot \operatorname{sinc}\left(\frac{t - nT}{T}\right)$$

lowpass filtering

$$x(t) = \left(\sum_{n=-\infty}^{\infty} x[n] \cdot \delta(t - nT) \right) * \operatorname{sinc}\left(\frac{t}{T}\right)$$



Bandpass sampling

Bandwidth less than f_s \longrightarrow e.g. a signal in the band $Nf_s \pm 0.5f_s$

Antialiasing filter: bandpass!

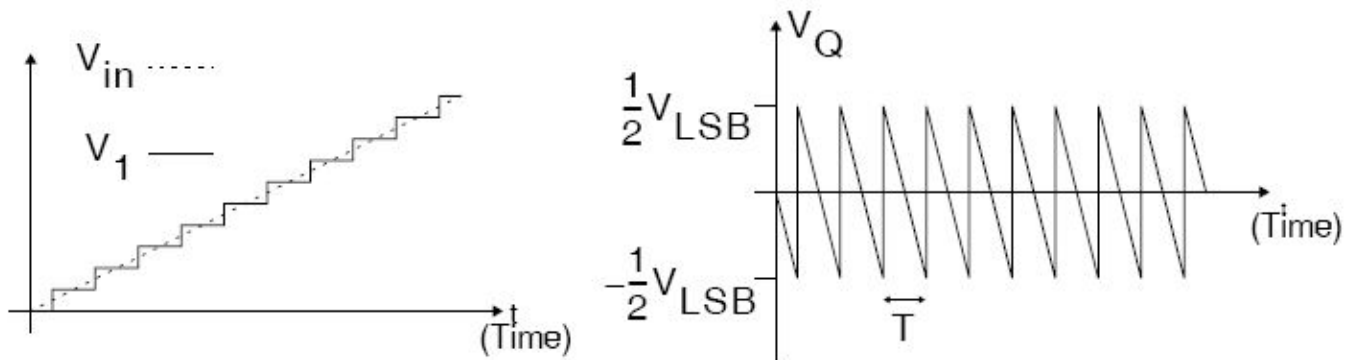
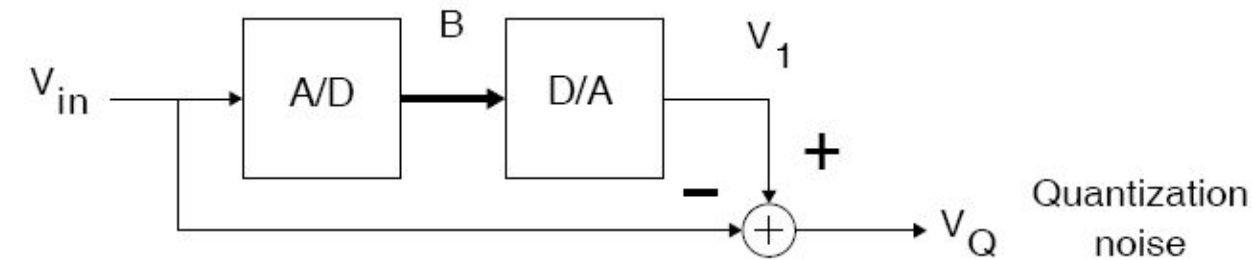
Reconstruction: with bandpass filter!

The influence of non-ideal sampling (*system bandwidth*) \longrightarrow unwanted lowpass filter.

Sampling jitter problem: present with Nyquist sampling, much sharper with bandpass sampling.

A/D noise

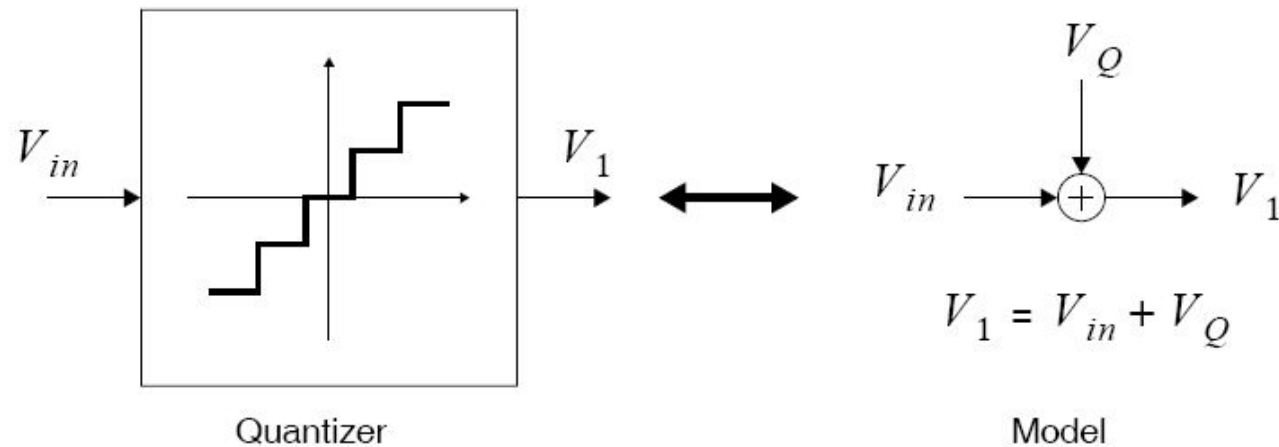
Quantization Noise



$$V_Q = V_1 - V_{in} \quad \text{or} \quad V_1 = V_{in} + V_Q \quad (8)$$

A/D noise

Quantization Noise



- Above model is exact
— approx made when assumptions made about V_Q
- Often assume V_Q is white, uniformly distributed
number between $\pm V_{\text{LSB}}/2$

A/D SNR

Noise amplitude: $q/2$, assumed uniformly distributed $\longrightarrow \sigma_n^2 = \frac{q^2}{12}$ (power).

Each extra bit gives 2x smaller q \longrightarrow 6.02 dB less noise.

SNR with assumption that “signal” is a maximum-amplitude ($2^N \cdot q$) sinusoid:

$$\begin{aligned} SNR &= 10 \log_{10} \frac{\text{signal power}}{\text{noise power}} [dB] = 10 \log_{10} \frac{(2^N q)^2 / (2 \cdot 2^2)}{q^2 / 12} [dB] = \\ &= 10 \log_{10} (1.5 * 4^N) [dB] = 1.76 + 6.02 \cdot N [dB] \end{aligned}$$

Oversampling

- More space for transition band of antialiasing filter (A/D) or reconstruction filter (D/A)
 - (AD) later we may LP filter and downsample signal: we gain 1 bit of accuracy for a 4-sample average; more gain with *noise shaping* → sigma-delta converters (not discussed further at ESPTR)
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D/A

- speed
 - bits
 - nonidealities
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