

# Ordered weighted enhancement of preference modeling in the reference point method for multiple criteria optimization

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**Abstract** The reference point method is an interactive technique for multiple criteria optimization problems. It is based on the optimization of the scalarizing achievement function built as the augmented max–min aggregation of individual outcomes with respect to the given reference levels. Actually, the worst individual achievement is optimized, but regularized with the term representing the average achievement. In order to avoid inconsistencies caused by the regularization, we apply the ordered weighted averages (OWA) with monotonic weights to combine all the individual achievements. Further, following the concept of the weighted OWA (WOWA), we incorporate the importance weighting of several achievements into the RPM. We show that the resulting WOWA RPM can be quite effectively implemented as an extension of the original constraints and criteria with simple linear inequalities.

**Keywords** Multicriteria decision making · Aggregation methods · Reference point method · OWA · WOWA

## 1 Introduction

Consider a decision problem defined as an optimization problem with  $m$  criteria (objective functions). In this paper, without loss of generality, it is assumed that all the criteria are maximized (that is, for each outcome ‘more is better’).

Hence, we consider the following multiple criteria optimization (MCO) problem:

$$\max\{(f_1(\mathbf{x}), \dots, f_m(\mathbf{x})) : \mathbf{x} \in Q\} \quad (1)$$

where  $\mathbf{x}$  denotes a vector of decision variables to be selected from the feasible set  $Q \subset R^n$ , and  $\mathbf{f}(x) = (f_1(\mathbf{x}), f_2(\mathbf{x}), \dots, f_m(\mathbf{x}))$  is a vector function that maps the feasible set  $Q$  into the criterion space  $R^m$ . Note that neither any specific form of the feasible set  $Q$  is assumed nor any special form of criteria  $f_i(\mathbf{x})$  is required. We refer to the elements of the criterion space as outcome vectors. An outcome vector  $\mathbf{y}$  is attainable if it expresses outcomes of a feasible solution, i.e.,  $\mathbf{y} = \mathbf{f}(\mathbf{x})$  for some  $\mathbf{x} \in Q$ . The set of all attainable outcome vectors will be denoted by  $Y$ .

The model (1) only specifies that we are interested in maximization of all objective functions  $f_i$  for  $i \in I = \{1, 2, \dots, m\}$ . Thus, it allows only to identify (to eliminate) obviously inefficient solutions leading to dominated outcome vectors, while still leaving the entire efficient set to look for a satisfactory compromise solution. In order to make the multiple criteria model operational for the decision support process, one needs to assume some solution concept well adjusted to the DM preferences. This can be achieved with the so-called quasi-satisficing approach to multiple criteria decision problems. The best formalization of the quasi-satisficing approach to multiple criteria optimization was proposed and developed mainly by Wierzbicki (1982) as the reference point method (RPM). The reference point method was later extended to permit additional information from the DM and, eventually, led to efficient implementations of the so-called aspiration/reservation-based decision support (ARBDS) approach with many successful applications (Granat and Makowski 2000; Lewandowski and Wierzbicki 1989; Malczewski and Ogryczak 1990; Ogryczak and Lahoda 1992; Wierzbicki et al. 2000).

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The RPM is an interactive technique. The basic concept of the interactive scheme is as follows. The DM specifies requirements in terms of reference levels, i.e., by introducing reference (target) values for several individual outcomes. Depending on the specified reference levels, a special scalarizing achievement function is built, which may be directly interpreted as expressing utility to be maximized. Maximization of the scalarizing achievement function generates an efficient solution to the multiple criteria problem. The computed efficient solution is presented to the DM as the current solution in a form that allows comparison with the previous solutions and modification of the reference levels if necessary.

The scalarizing achievement function can be viewed as two-stage transformation of the original outcomes. First, the strictly monotonic component achievement functions are built to measure individual performance with respect to given reference levels. Having all the outcomes transformed into a uniform scale of individual achievements, they are aggregated at the second stage to form a unique scalarization. The RPM is based on the so-called augmented (or regularized) max–min aggregation. Thus, the worst individual achievement is essentially maximized, but the optimization process is additionally regularized with the term representing the average achievement. The max–min aggregation guarantees fair treatment of all individual achievements by implementing an approximation to the Rawlsian principle of justice.

The max–min aggregation is crucial for allowing the RPM to generate all efficient solutions even for nonconvex (and particularly discrete) problems. On the other hand, the regularization is necessary to guarantee that only efficient solutions are generated. The regularization by the average achievement is easily implementable, but it may disturb the basic max–min model. Actually, the only consequent regularization of the max–min aggregation is the lex-min order or, more practical, the OWA aggregation with monotonic weights. The latter combines all the component achievements allocating the largest weight to the worst achievement, the second largest weight to the second worst achievement, the third largest weight to the third worst achievement, and so on. The recent progress in optimization methods for ordered averages (Ogryczak and Śliwiński 2003) allows one to implement the OWA RPM quite effectively. Further, following the concept of weighted OWA (Torra 1997; Torra and Narukawa 2007), the importance weighting of several achievements may be incorporated into the RPM. Such a WOWA enhancement of the RPM uses importance weights to affect achievement importance by rescaling accordingly its measure within the distribution of achievements rather than straightforward rescaling of achievement values (Ruiz et al. 2009). The

paper analyzes both the theoretical and implementation issues of the WOWA-enhanced RPM.

The paper is organized as follows. In the next section the scalarizing achievement functions are discussed and related to the fuzzy multicriteria optimization. In Sect. 3, the OWA refinement of the RPM is introduced and analyzed. The OWA RPM model is further extended in Sect. 4 to accommodate the importance weights following the WOWA methodology. Linear programming computational model for the WOWA RPM method is introduced. In Sect. 5, an illustrative example is discussed.

## 2 RPM and fuzzy targets

In the RPM method, depending on the specified reference levels, a special scalarizing achievement function is built which, when optimized, generates an efficient solution to the problem. While building the scalarizing achievement function, some basic properties of the preference model are assumed. First of all, the following property is required:

**P1** The preference model corresponding to the scalarizing achievement function optimization is consistent with the Pareto order and therefore each solution generated by the scalarizing function optimization is an efficient solution of the original MCO problem.

To meet this requirement, the preference model corresponding to the scalarizing achievement function optimization is strictly monotonic in the sense that an increase of any outcome  $y_i$  leads to a preferred solution. Actually, the function must strictly increase with respect to each individual outcome.

Second, the scalarizing achievement function optimization must enforce reaching the reference levels prior to further improving of criteria. Hence, the following property is required:

**P2** The preference model corresponding to the scalarizing achievement function optimization guarantees that a solution with all individual outcomes satisfying the corresponding reference levels is preferred to any solution with at least one individual outcome worse than its reference level.

Thus, similar to the goal programming approaches, the reference levels are treated as targets, but following the quasi-satisficing approach, they are interpreted consistently with basic concepts of efficiency in the sense that the optimization is continued even when the target point has been reached already (Wierzbicki et al. 2000).

The generic scalarizing achievement function takes the following form (Wierzbicki 1982):

$$S(\mathbf{a}) = \min_{1 \leq i \leq m} \{a_i\} + \frac{\varepsilon}{m} \sum_{i=1}^m a_i \tag{2}$$

where  $\varepsilon$  is an arbitrary small positive number and  $a_i = s_i(f_i(\mathbf{x}))$  for  $i = 1, 2, \dots, m$  are the component achievements measuring actual performances of the individual outcomes with component achievement functions  $s_i : R \rightarrow R$  for  $i = 1, 2, \dots, m$  defined with respect to the corresponding reference levels. Let  $a_i$  denote the component achievement for the  $i$ th outcome ( $a_i = s_i(y_i) = s_i(f_i(\mathbf{x}))$ ), and let  $\mathbf{a} = (a_1, a_2, \dots, a_m) = \mathbf{s}(\mathbf{y})$  represent the entire achievement vector. During the interactive analysis, the scalarizing achievement function is maximized in order to generate an efficient solution as a current solution, i.e.,

$$\max_{\mathbf{x} \in Q} S(\mathbf{s}(\mathbf{f}(\mathbf{x}))) = \max_{\mathbf{a} \in A} S(\mathbf{a}) \tag{3}$$

where

$$A = \{\mathbf{a} = \mathbf{s}(\mathbf{y}) : \mathbf{y} \in Y\} = \{\mathbf{a} = \mathbf{s}(\mathbf{f}(\mathbf{x})) : \mathbf{x} \in Q\}. \tag{4}$$

Note that we will use simplified notation of optimization over the achievement set  $A$ , although still assuming that according to Eq. 4 the optimal solution  $\bar{\mathbf{a}}$  is generated by an optimal decision vector  $\bar{\mathbf{x}}$  such that  $\bar{\mathbf{a}} = \mathbf{s}(\mathbf{f}(\bar{\mathbf{x}}))$ .

The scalarizing achievement function (2) is essentially defined by the worst component achievement, but additionally regularized with the sum of all component achievements. The regularization term is introduced in order to guarantee the efficiency of the optimal solution in the case when the maximization of the main term (the worst component achievement) results in a non-unique optimal solution. Due to combining two terms with an arbitrarily small parameter  $\varepsilon$ , formula (2) is easily implementable and provides a direct interpretation of the scalarizing achievement function as expressing utility. When accepting the loss of a direct utility interpretation, one may consider a limiting case with  $\varepsilon \rightarrow 0_+$ , which results in lexicographic order applied to two separate terms of function (2). That means, the regularization can be implemented with the second level lexicographic optimization (Ogryczak and Lahoda 1992). Therefore, RPM may be also considered as the following lexicographic problem (Ogryczak 2001 and references therein):

$$\text{lex max}_{\mathbf{a} \in A} \left( \min_{1 \leq i \leq m} a_i, \sum_{i=1}^m a_i \right) \tag{5}$$

Various functions  $s_i$  provide a wide modeling environment for measuring component achievements (Wierzbicki 1986; Wierzbicki et al. 2000; Miettinen and Mäkelä 2002; Malczewski and Ogryczak 1996; Ogryczak 1997). The basic RPM model is based on the single vector of the reference levels, the aspiration vector  $\mathbf{r}^a$ . For the

sake of computational simplicity, the piecewise linear functions  $s_i$  are usually employed. In the simplest models, and they take the form of two segment piecewise linear functions:

$$s_i(y_i) = \begin{cases} \lambda_i^+(y_i - r_i^a), & \text{for } y_i \geq r_i^a \\ \lambda_i^-(y_i - r_i^a), & \text{for } y_i < r_i^a \end{cases} \tag{6}$$

where  $\lambda_i^+ > \lambda_i^-$  are positive scaling factors corresponding to underachievements and overachievements, respectively, for the  $i$ th outcome. It is usually assumed that  $\lambda_i^+$  is much larger than  $\lambda_i^-$ . Figure 1 depicts how differentiated scaling affects the isoline contours of the scalarizing achievement function.

Real-life applications of the RPM methodology usually deal with more complex component achievement functions defined with more than one reference point (Wierzbicki et al. 2000), which enriches the preference models and simplifies the interactive analysis. In particular, the models taking advantages of two reference vectors: vector of aspiration levels  $\mathbf{r}^a$  and vector of reservation levels  $\mathbf{r}^r$  (Lewandowski and Wierzbicki 1989) are used, thus allowing the DM to specify requirements by introducing acceptable and required values for several outcomes. The component achievement function  $s_i$  can be interpreted then as a measure of the DM's satisfaction with the current outcome value of the  $i$ th criterion. It is a strictly increasing function of outcome  $y_i$  with value  $a_i = 1$  if  $y_i = r_i^a$ , and  $a_i = 0$  for  $y_i = r_i^r$ . Thus, the component achievement functions map the outcomes values onto a normalized scale of the DM's satisfaction. Various functions can be built meeting those requirements. We use the piecewise linear component achievement function introduced in an implementation of the ARBDS system for the multiple criteria transshipment problems with facility location (Ogryczak et al. 1992):

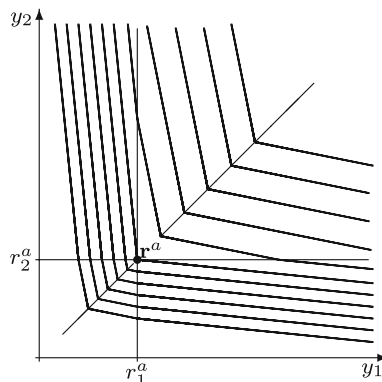


Fig. 1 Isoline contours for the scalarizing achievement function (2) with component achievements (6)

$$s_i(y_i) = \begin{cases} \gamma \frac{y_i - r_i^r}{r_i^a - r_i^r}, & y_i \leq r_i^r \\ \gamma \frac{y_i - r_i^r}{r_i^a - r_i^r}, & r_i^r < y_i < r_i^a \\ \alpha \frac{y_i - r_i^a}{r_i^a - r_i^r} + 1, & y_i \geq r_i^a \end{cases} \quad (7)$$

where  $\alpha$  and  $\gamma$  are arbitrary parameters satisfying  $0 < \alpha < 1 < \gamma$ . The parameter  $\alpha$  represents additional increase of the DM's satisfaction over level 1 when a criterion generates outcomes better than the corresponding aspiration level. On the other hand, the parameter  $\gamma > 1$  represents dissatisfaction connected with outcomes worse than the reservation level (Fig. 2).

The lexicographic RPM model (5) used with the component achievement function (7) guarantees that the crucial properties of the quasi-satisficing decision model are fulfilled. Indeed, the following theorem is valid (Ogryczak 1994).

**Theorem 1** *The preference model corresponding to the lexicographic optimization (5) and (7) has the following properties:*

1. *It is strictly monotonic in the sense that an increase of any outcome  $y_i$  leads to a preferred solution.*
2. *It guarantees that for any given target value  $q$ , the solution generating all component achievements equal to  $q$  ( $a_i = q \forall i$ ) is preferred to any solution generating at least one component achievement worse than  $q$ .*

Note that following the property 1, every solution optimal to the lexicographic optimization (5) with (7) is an efficient solution to the MCO problem (the property P1). Further, following the property 2, the solution reaching all the reservation levels is preferred to any solution failing to achieve at least one reservation level ( $q = 0$ ) as well as the solution reaching all the aspiration levels is preferred to any solution failing to achieve at least one aspiration level ( $q = 1$ ). Thus, the property P2 is satisfied in terms of the ARBDS methodology. Note that this property is only approximated in the case of the analytic scalarizing achievement function (2) since the regularization term may disturb those preferences.

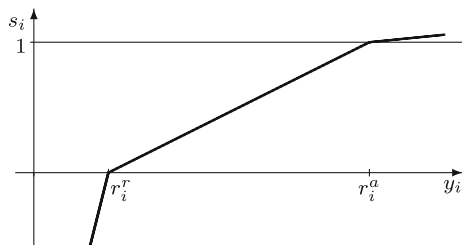


Fig. 2 Component achievement function (7)

For outcomes between the reservation and the aspiration levels, the component achievement function  $s_i$  can be interpreted as a membership function  $\mu_i$  for a fuzzy target (Zimmermann 1996).

$$\mu_i(y_i) = \begin{cases} 0, & y_i \leq r_i^r \\ \frac{y_i - r_i^r}{r_i^a - r_i^r}, & r_i^r < y_i < r_i^a \\ 1, & y_i \geq r_i^a \end{cases} \quad (8)$$

However, such a membership function remains constant with value 1 for all outcomes greater than the corresponding aspiration level, and with value 0 for all outcomes below the reservation level (Fig. 3). Hence, the fuzzy membership function is neither strictly monotonic nor concave, thus not representing typical utility for a maximized outcome. The component achievement function (7) can be viewed as an extension of the fuzzy membership function to a strictly monotonic and concave utility. One may also notice that the aggregation scheme used to build the scalarizing achievement function (2) from the component functions may also be interpreted as some fuzzy aggregation operator (Wierzbicki et al. 2000). In other words, maximization of the scalarizing achievement function (2) is consistent with the fuzzy methodology in the case of not attainable aspiration levels and satisfiable all reservation levels while modeling a reasonable utility for any values of aspiration and reservation levels.

**Theorem 2** *If outcome vector  $\bar{y} \in Y$  generates an optimal solution of the lexicographic RPM problem (5) with the piecewise linear component achievement functions (7), then  $\bar{y}$  is an optimal solution of the corresponding fuzzy targets intersection optimization problem*

$$\max_{y \in Y} [\min_{1 \leq i \leq m} \mu_i(y_i)] \quad (9)$$

*Proof* Let  $\bar{a} = \mathbf{s}(\bar{y})$ , with  $s_i$  defined according to (7), be an optimal solution of the lexicographic RPM problem (5). Suppose that  $\bar{y}$  is not optimal to problem (9). This means  $\min_{1 \leq i \leq m} \mu_i(\bar{y}_i) = \mu_{i_0}(\bar{y}_{i_0}) = \bar{q} < 1$  and there exists  $\tilde{y} \in Y$  such that  $\mu_i(\tilde{y}_i) \geq \tilde{q} > \bar{q}$  for all  $i \in I$ . Note that  $\bar{q} < 1$  and  $\tilde{q} > 0$ . Hence,  $s_i(\tilde{y}_i) \geq \mu_i(\tilde{y}_i)$  for all  $i \in I$  and  $\mu_{i_0}(\bar{y}_{i_0}) \geq s_{i_0}(\bar{y}_{i_0})$ . Thus,  $s_i(\tilde{y}_i) \geq \tilde{q} > \bar{q} \geq s_{i_0}(\bar{y}_{i_0}) \geq \min_{1 \leq i \leq m} s_i(\bar{y}_i)$ , which contradicts optimality of  $\bar{y}$  with respect to the maxmin optimization  $\max_{y \in Y} [\min_{1 \leq i \leq m} s_i(y_i)]$  and also to the lexicographic RPM problem (5).

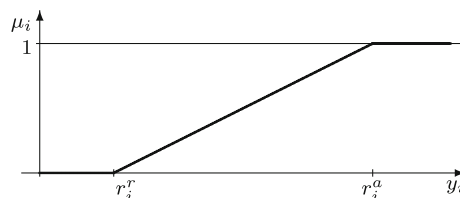


Fig. 3 Fuzzy membership function (8)

Under the assumption that the parameters  $\alpha$  and  $\gamma$  and satisfy inequalities  $0 < \alpha < 1 < \gamma$ , the component achievement function (7) strictly increases and is concave. Hence, it can be expressed in the form:

$$s_i(y_i) = \min \left\{ \gamma \frac{y_i - r_i^r}{r_i^a - r_i^r}, \frac{y_i - r_i^r}{r_i^a - r_i^r}, \alpha \frac{y_i - r_i^a}{r_i^a - r_i^r} + 1 \right\},$$

which guarantees LP computability with respect to outcomes  $y_i$ . Finally, maximization of the entire scalarizing achievement function (5) can be implemented by the following auxiliary LP constraints:

$$\begin{aligned} &\text{lex max} \left( \underline{a}, \sum_{i=1}^m a_i \right) \\ &\text{s.t. } \underline{a} \leq a_i \quad \forall i \in I \\ &a_i \leq \gamma \frac{y_i - r_i^r}{r_i^a - r_i^r} \quad \forall i \in I \\ &a_i \leq \frac{y_i - r_i^r}{r_i^a - r_i^r} \quad \forall i \in I \\ &a_i \leq \alpha \frac{y_i - r_i^a}{r_i^a - r_i^r} + 1 \quad \forall i \in I \end{aligned}$$

where  $a_i$  for  $i = 1, \dots, m$  and  $\underline{a}$  are unbounded variables introduced to represent values of several component achievement functions and their minimum, respectively.

On the other hand, the fuzzy model (9) requires the use of some binary variables. In the simplest form it can be formulated as follows:

$$\begin{aligned} &\text{max } \underline{a} \\ &\text{s.t. } \underline{a} \leq a_i \quad \forall i \in I \\ &a_i \leq 1 - u_i \quad \forall i \in I \\ &a_i \leq \frac{y_i - r_i}{a_i - r_i} + M u_i \quad \forall i \in I \\ &u_i \leq \frac{r_i - y_i}{M(a_i - r_i)} + 1 \quad \forall i \in I \end{aligned}$$

where  $M$  is a large constant and  $u_i$  are binary variables satisfying  $y_i > r_i \Rightarrow u_i = 0$ , due to the last inequality. Hence, the lexicographic RPM problem (5) with the piecewise linear component achievement functions (7) allow us to select efficient solutions among various alternative optimal solutions of the corresponding fuzzy targets intersection optimization problem (9). Simultaneously, the corresponding RPM problem is much more simpler with respect to its computational complexity.

### 3 OWA refinement of the RPM

The crucial properties of the RPM are related to the max–min aggregation of the component achievements. The regularization is introduced in order to guarantee the

aggregation monotonicity. Unfortunately, the distribution of achievements may make the max–min criterion partially passive when one specific achievement is relatively very small for all the solutions. Maximization of the worst achievement may then leave all other achievements un-optimized. The selection is then made according to linear aggregation of the regularization term instead of the max–min aggregation, thus destroying the preference model of the RPM. This can be illustrated with an example of a simple discrete problem of seven alternative feasible solutions to be selected according to six criteria. Table 1 presents six component achievements for all the solutions, where the component achievements have been defined according to the aspiration/reservation model (7), thus allocating 1 to outcomes reaching the corresponding aspiration level. All the solutions are efficient. Solution S1–S5 reach aspiration levels (achievement values 1.0) for four of the first five criteria while failing to reach one of them and the aspiration level for the sixth criterion as well (achievement values 0.1). Solution S6 is close to the aspiration levels (achievement values 0.8) for the first five criteria while failing to reach the aspiration level for the sixth criterion (achievement values 0.1). All the solutions generate the same worst achievement value of 0.1 and the final selection of the RPM depends on the total achievement (regularization term). Actually, one of solutions of S1–S5 will be selected as better than S6.

One may easily notice that eliminating from the consideration alternative S7, we get the sixth component achievement (and the corresponding criterion) constant for the six alternatives under consideration. Hence, one may expect the same solution selected while taking into account this criterion or not. If focusing on five first criteria, then the RPM (either lexicographic (5) or analytic (2)) obviously selects solution S6 as reaching the worst achievement value of 0.8.

In order to avoid inconsistencies caused by the regularization, the max–min solution may be regularized according to the ordered averaging rules (Yager 1988). This is mathematically formalized as follows. Within the

**Table 1** Sample achievements with passive max–min criterion

Sol.	$a_1$	$a_2$	$a_3$	$a_4$	$a_5$	$a_6$	Min	$\Sigma$
S1	0.1	1.0	1.0	1.0	1.0	0.1	0.1	4.2
S2	1.0	0.1	1.0	1.0	1.0	0.1	0.1	4.2
S3	1.0	1.0	0.1	1.0	1.0	0.1	0.1	4.2
S4	1.0	1.0	1.0	0.1	1.0	0.1	0.1	4.2
S5	1.0	1.0	1.0	1.0	0.1	0.1	0.1	4.2
S6	0.8	0.8	0.8	0.8	0.8	0.1	0.1	4.1
S7	0.1	0.1	0.1	0.8	0.4	0.8	0.1	2.3



space of achievement vectors, we introduce map  $\Theta = (\theta_1, \theta_2, \dots, \theta_m)$ , which orders the coordinates of achievements vectors in a nonincreasing order, i.e.,  $\Theta(a_1, a_2, \dots, a_m) = (\theta_1(\mathbf{a}), \theta_2(\mathbf{a}), \dots, \theta_m(\mathbf{a}))$  if there exists a permutation  $\tau$  such that  $\theta_i(\mathbf{a}) = a_{\tau(i)}$  for all  $i$  and  $\theta_1(\mathbf{a}) \geq \theta_2(\mathbf{a}) \geq \dots \geq \theta_m(\mathbf{a})$ . The standard max–min aggregation depends on maximization of  $\theta_m(\mathbf{a})$  and it ignores values of  $\theta_i(\mathbf{a})$  for  $i \leq m - 1$ . In order to take into account all the achievement values, one needs to maximize the weighted combination of the ordered achievements thus representing the so-called ordered weighted averaging (OWA) aggregation (Yager 1988). Note that the weights are then assigned to the specific positions within the ordered achievements rather than to the component achievements themselves. With the OWA aggregation, one gets the following RPM model:

$$\max_{\mathbf{a} \in A} \sum_{i=1}^m w_i \theta_i(\mathbf{a}) \tag{10}$$

where  $w_1 < w_2 < \dots < w_m$  are positive and strictly increasing weights. Actually, they should be significantly increasing to represent regularization of the max–min order. When differences among weights tend to infinity, the OWA aggregation approximates the leximin ranking of the ordered outcome vectors (Yager 1997). Note that the standard RPM model with the scalarizing achievement function (2) can be expressed as the following OWA model:

$$\max_{\mathbf{a} \in A} \left( \left( 1 + \frac{\varepsilon}{m} \right) \theta_m(\mathbf{a}) + \frac{\varepsilon}{m} \sum_{i=1}^{m-1} \theta_i(\mathbf{a}) \right)$$

Hence, the standard RPM model exactly represents the OWA aggregation (10) with strictly increasing weights in the case of  $m = 2$  ( $w_1 = \varepsilon/2 < w_2 = 1 + \varepsilon/2$ ). For  $m > 2$  it abandons the differences in weighting of the largest achievement, the second largest one, etc. ( $w_1 = \dots = w_{m-1} = \varepsilon/m$ ). The OWA RPM model (10) allows one to distinguish all the weights by introducing increasing series (e.g., geometric ones). One may notice in Table 2 that application of increasing weights  $\mathbf{w} = (0.02, 0.03, 0.05, 0.15, 0.25, 0.5)$  within the OWA RPM enables the selection of solution S6 from Table 1. On the other hand, the OWA RPM model (10), similar to that of (2), does not fulfill completely the preference model of the reference vectors (property P2).

When accepting the loss of a direct utility interpretation, one may consider more powerful lexicographic preference modeling (Ogryczak 1997, 2001) based on the linear component achievement function

$$a_i = s_i(f_i(\mathbf{x})) = (f_i(\mathbf{x}) - r_i^r) / (r_i^a - r_i^r) \quad \forall i \in I \tag{11}$$

but split into separate preemptive multilevel interval achievement measures: the reservation level underachievement

**Table 2** Ordered achievements values

Sol.	$\theta_1$	$\theta_2$	$\theta_3$	$\theta_4$	$\theta_5$	$\theta_6$	$A_{\mathbf{w}}$
S1	1.0	1.0	1.0	1.0	0.1	0.1	0.505
S2	1.0	1.0	1.0	1.0	0.1	0.1	0.505
S3	1.0	1.0	1.0	1.0	0.1	0.1	0.505
S4	1.0	1.0	1.0	1.0	0.1	0.1	0.505
S5	1.0	1.0	1.0	1.0	0.1	0.1	0.505
S6	0.8	0.8	0.8	0.8	0.8	0.1	0.630
S7	0.8	0.8	0.4	0.1	0.1	0.1	0.285
$\mathbf{w}$	0.02	0.03	0.05	0.15	0.25	0.5	

$$a_i^r = s_i^r(f_i(\mathbf{x})) = \frac{(r_i^r - f_i(\mathbf{x}))_+}{r_i^a - r_i^r} \quad \forall i \in I,$$

the aspiration level underachievement

$$a_i^a = s_i^a(f_i(\mathbf{x})) = \min \left\{ \frac{(r_i^a - f_i(\mathbf{x}))_+}{r_i^a - r_i^r}, 1 \right\} \quad \forall i \in I$$

and the aspiration level overachievement

$$a_i^o = s_i^o(f_i(\mathbf{x})) = \frac{(f_i(\mathbf{x}) - r_i^a)_+}{r_i^a - r_i^r} \quad \forall i \in I.$$

Taking into account (11), they can be rewritten as

$$\begin{aligned} a_i^r &= (-a_i)_+ \quad \forall i \in I \\ a_i^a &= \min \{ (1 - a_i)_+, 1 \} \quad \forall i \in I. \\ a_i^o &= (a_i - 1)_+ \quad \forall i \in I \end{aligned} \tag{12}$$

For instance, sample achievements from Table 1 represent all the results between the reservation and aspiration levels. Hence, the corresponding reservation underachievements are equal to zero ( $\mathbf{a}^r = 0$ ) and similarly all the aspiration overachievements ( $\mathbf{a}^o = 0$ ), while the aspiration underachievement are given in Table 3.

Maximization of the scalarizing achievement function (10) is replaced with the lexicographic minimization of the multilevel aggregations:

$$\text{lex} \min_{\mathbf{a} \in A} \{ (A_{\mathbf{w}}(\mathbf{a}^r), A_{\mathbf{w}}(\mathbf{a}^a), A_{\mathbf{w}}(-\mathbf{a}^o)) : \text{Eqs. (11) - (12)} \} \tag{13}$$

with positive and strictly decreasing weights  $w_1 > w_2 > \dots > w_m > 0$ . One may notice in Table 4 that application of decreasing weights  $\mathbf{w} = (0.5, 0.25, 0.15, 0.05, 0.03, 0.02)$  within the OWA RPM (13) enables the selection of solution S6 from Table 3.

Problem (13) always generates an efficient solution to the original MCO problem complying simultaneously with the ARBDS preference model assumptions.

**Theorem 3** For any reference levels  $r_i^a > r_i^r$ , any positive weights  $\mathbf{w}$ , if  $(\bar{\mathbf{a}}^r, \bar{\mathbf{a}}^a, \bar{\mathbf{a}}^o)$  is an optimal solution of the problem (13) then any decision vector  $\bar{\mathbf{x}} \in Q$  generating

**Table 3** Sample aspiration underachievements

Sol.	$a_1^a$	$a_2^a$	$a_3^a$	$a_4^a$	$a_5^a$	$a_6^a$
S1	0.9	0.0	0.0	0.0	0.0	0.9
S2	0.0	0.9	0.0	0.0	0.0	0.9
S3	0.0	0.0	0.9	0.0	0.0	0.9
S4	0.0	0.0	0.0	0.9	0.0	0.9
S5	0.0	0.0	0.0	0.0	0.9	0.9
S6	0.2	0.2	0.2	0.2	0.2	0.9
S7	0.9	0.9	0.9	0.2	0.6	0.2

**Table 4** Ordered aspiration underachievements with passive min-max criterion

Sol.	$\theta_1$	$\theta_2$	$\theta_3$	$\theta_4$	$\theta_5$	$\theta_6$	$A_w(\mathbf{a}^a)$
S1	0.9	0.9	0.0	0.0	0.0	0.0	0.675
S2	0.9	0.9	0.0	0.0	0.0	0.0	0.675
S3	0.9	0.9	0.0	0.0	0.0	0.0	0.675
S4	0.9	0.9	0.0	0.0	0.0	0.0	0.675
S5	0.9	0.9	0.0	0.0	0.0	0.0	0.675
S6	0.9	0.2	0.2	0.2	0.2	0.2	0.550
S7	0.9	0.9	0.9	0.6	0.2	0.2	0.895
<b>w</b>	0.5	0.25	0.15	0.05	0.03	0.02	

this solution is an efficient solution of the corresponding MCO problem (1).

*Proof* Let  $\bar{\mathbf{x}}$  be a feasible vector generating  $(\bar{\mathbf{a}}^r, \bar{\mathbf{a}}^a, \bar{\mathbf{a}}^o)$  optimal to the problem (13) with some positive weight vector  $\mathbf{w}$ . Suppose that  $\bar{\mathbf{x}}$  is not efficient to the MCO problem (1). This means that there exists a decision vector  $\mathbf{x} \in Q$  such that  $f_i(\mathbf{x}) \geq f_i(\bar{\mathbf{x}})$  for all  $i \in I$  and  $f_{i_o}(\mathbf{x}) > f_{i_o}(\bar{\mathbf{x}})$  for some outcome index  $i_o \in I$ . Let us define  $a_i^r, a_i^a$  and  $a_i^o$  according to formula (12). The triple  $(\mathbf{a}^r, \mathbf{a}^a, \mathbf{a}^o)$  is then a feasible solution of the problem (13). Moreover,  $a_i^r \leq \bar{a}_i^r, a_i^a \leq \bar{a}_i^a$  and  $a_i^o \geq \bar{a}_i^o$  for all  $i \in I$ , where at least one of strict inequalities  $a_{i_o}^r < \bar{a}_{i_o}^r$  or  $a_{i_o}^a < \bar{a}_{i_o}^a$  or  $a_{i_o}^o > \bar{a}_{i_o}^o$  holds. Hence, due to strict monotonicity of the OWA aggregation with positive weighting vectors, one gets  $A_w(\mathbf{a}^r) \leq A_w(\bar{\mathbf{a}}^r), A_w(\mathbf{a}^a) \leq A_w(\bar{\mathbf{a}}^a)$  and  $A_w(-\mathbf{a}^o) \leq A_w(-\bar{\mathbf{a}}^o)$  with at least one inequality strict. The latest assertion contradicts the lexicographic optimality of  $(\bar{\mathbf{a}}^r, \bar{\mathbf{a}}^a, \bar{\mathbf{a}}^o)$  for problem (13), which completes the proof.

**Theorem 4** For any reference levels  $r_i^a > r_i^r$ , any positive weights  $\mathbf{w}$ , if  $(\bar{\mathbf{a}}^r, \bar{\mathbf{a}}^a, \bar{\mathbf{a}}^o)$  is an optimal solution of the problem (13), then all the reservation level underachievements  $\bar{a}_i^r$  are equal to 0 whenever there exists a feasible solution  $\mathbf{x} \in Q$  such that  $f_i(\mathbf{x}) \geq r_i^r$  for all  $i \in I$ .

*Proof* Let  $(\bar{\mathbf{a}}^r, \bar{\mathbf{a}}^a, \bar{\mathbf{a}}^o)$  be an optimal solution of the problem (13) with some positive weight vector  $\mathbf{w}$ . Suppose

that  $\bar{a}_{i_0}^r < 0$  for some  $i_0 \in I$  and there exists a feasible solution  $\mathbf{x} \in Q$  such that  $f_i(\mathbf{x}) \geq r_i^r$  for all  $i \in I$ . Let us define  $a_i^r, a_i^a$  and  $a_i^o$  according to formula (12) and note that  $a_i^r = 0$  for all  $i \in I$ . The triple  $(\mathbf{a}^r, \mathbf{a}^a, \mathbf{a}^o)$  is then a feasible solution of problem (26) and, due to positive weights,  $A_w(\mathbf{a}^r) = 0 < A_w(\bar{\mathbf{a}}^r)$ , thus contradicting the lexicographic optimality of  $(\bar{\mathbf{a}}^r, \bar{\mathbf{a}}^a, \bar{\mathbf{a}}^o)$ .

**Theorem 5** For any reference levels  $r_i^a > r_i^r$ , any positive weights  $\mathbf{w}$ , if  $(\bar{\mathbf{a}}^r, \bar{\mathbf{a}}^a, \bar{\mathbf{a}}^o)$  is an optimal solution of the problem (13), then all the aspiration level underachievements  $\bar{a}_i^a$  are equal to 0 whenever there exists a feasible solution  $\mathbf{x} \in Q$  such that  $f_i(\mathbf{x}) \geq r_i^a$  for all  $i \in I$ .

*Proof* Let  $(\bar{\mathbf{a}}^r, \bar{\mathbf{a}}^a, \bar{\mathbf{a}}^o)$  be an optimal solution of the problem (13) with some positive weight vector  $\mathbf{w}$ . Suppose that  $\bar{a}_{i_0}^a < 0$  for some  $i_0 \in I$  and there exists a feasible solution  $\mathbf{x} \in Q$  such that  $f_i(\mathbf{x}) \geq r_i^a$  for all  $i \in I$ . Let us define  $a_i^r, a_i^a$  and  $a_i^o$  according to formula (12) and note that  $a_i^a = a_i^r = 0$  for all  $i \in I$ . The triple  $(\mathbf{a}^r, \mathbf{a}^a, \mathbf{a}^o)$  is then a feasible solution of problem (26) and, due to positive weights,  $A_w(\mathbf{a}^a) = 0 < A_w(\bar{\mathbf{a}}^a)$ , thus contradicting the lexicographic optimality of  $(\bar{\mathbf{a}}^r, \bar{\mathbf{a}}^a, \bar{\mathbf{a}}^o)$ .

Note that following Theorem 3, every solution optimal to the OWA RPM problem (13) is an efficient solution to the MCO problem (property P1). Further, following Theorem 4, a solution reaching all the reservation levels is preferred to any solution failing achievement of at least one reservation level. Similarly, according to Theorem 5, a solution reaching all the aspiration levels is preferred to any solution failing achievement of at least one aspiration level. Thus, the property P2 is satisfied in terms of the ARBDS methodology. The following theorem shows that for each efficient solution  $\bar{\mathbf{x}}$  there exist aspiration and reservation vectors such that  $\bar{\mathbf{x}}$  with the corresponding values of the multilevel achievements is an optimal solution of the problem (13), thus justifying the complete controllability of the interactive process by the aspiration levels.

**Theorem 6** If  $\bar{\mathbf{x}}$  is an efficient solution of the MCO problem (1), then there exist aspirations levels  $r_i^a$  such that the corresponding triple  $(\bar{\mathbf{a}}^r, \bar{\mathbf{a}}^a, \bar{\mathbf{a}}^o)$  is an optimal solution of problem (13), for any reservation levels  $r_i^r < r_i^a$  and any positive weight vector  $\mathbf{w}$ .

*Proof* Let us set the aspiration levels as  $r_i^a = f_i(\bar{\mathbf{x}})$  for  $i \in I$ . For any reservation levels  $r_i^r < r_i^a$ , all the corresponding multilevel achievements defined according to the formula (12) take the zero values:  $\bar{\mathbf{a}}^r = 0, \bar{\mathbf{a}}^a = 0$  and  $\bar{\mathbf{a}}^o = 0$ . Suppose that for some weights the triple  $(0, 0, 0)$  is not an optimal solution of the corresponding problem (13). This means that there exists a vector  $\mathbf{x} \in Q$  such that  $\mathbf{a}^r = 0, \mathbf{a}^a = 0, \mathbf{a}^o \geq 0$  and  $A_w(-\mathbf{a}^o) < A_w(-\bar{\mathbf{a}}^o)$ . Hence,  $f_i(\mathbf{x}) \geq f_i(\bar{\mathbf{x}}) \quad \forall i \in I$  and  $f_{i_o}(\mathbf{x}) > f_{i_o}(\bar{\mathbf{x}})$  for some index  $i_o \in$

I. The latest assertion contradicts the efficiency of  $\bar{\mathbf{x}}$  to the MCO problem (1), which completes the proof.

Note that instead of (12), the interval achievements may be defined with the goal programming modeling techniques (Ogryczak and Lahoda 1992):

$$\begin{aligned} a_i &= (f_i(\mathbf{x}) - r_i^r)/(r_i^a - r_i^r), \quad \forall i \in I \\ a_i - a_i^o + a_i^a + a_i^r &= -1, \quad \forall i \in I \\ a_i^o \geq 0, 0 \leq a_i^a \leq 1, a_i^r &\geq 0 \quad \forall i \in I \end{aligned} \tag{14}$$

Indeed, due to strict monotonicity of the OWA aggregation with positive weights (Kostreva and Ogryczak 1999; Llamazares 2004), the following assertion may be applied to justify the OWA RPM model given as

$$\text{lex min}_{\mathbf{a} \in A} \{ (A_w(\mathbf{a}^r), A_w(\mathbf{a}^a), A_w(-\mathbf{a}^o)) : \text{Eq. (14)} \}. \tag{15}$$

**Lemma 1** For any strictly increasing scalarizing function  $g$ , if  $(\bar{\mathbf{x}}, \bar{\mathbf{a}}^r, \bar{\mathbf{a}}^a, \bar{\mathbf{a}}^o)$  is an optimal solution of the problem.

$$\text{lex min}_{\mathbf{a} \in A} \{ (g(\mathbf{a}^r), g(\mathbf{a}^a), g(-\mathbf{a}^o)) : \text{Eq. (14)} \}, \tag{16}$$

then it is an optimal solution of the problem

$$\text{lex min}_{\mathbf{a} \in A} \{ (g(\mathbf{a}^r), g(\mathbf{a}^a), g(-\mathbf{a}^o)) : \text{Eq. (11) - (12)} \}. \tag{17}$$

*Proof* Let  $(\bar{\mathbf{x}}, \bar{\mathbf{a}}^r, \bar{\mathbf{a}}^a, \bar{\mathbf{a}}^o)$  be an optimal solution of the problem (16). If  $\bar{a}_i^r, \bar{a}_i^a$  and  $\bar{a}_i^o$  fulfill the formula (12) for  $\bar{\mathbf{x}}$ , then the quadruple  $(\bar{\mathbf{x}}, \bar{\mathbf{a}}^r, \bar{\mathbf{a}}^a, \bar{\mathbf{a}}^o)$  is an optimal solution of the corresponding problem (17). In order to prove that the formula (12) is satisfied, it is sufficient to show that  $\bar{a}_i^o \bar{a}_i^a = 0$  and  $(1 - \bar{a}_i^a) \bar{a}_i^r = 0$  for all  $i \in I$  while obviously  $\bar{a}_i^o \bar{a}_i^a \geq 0$  and  $(1 - \bar{a}_i^a) \bar{a}_i^r \geq 0$  for all  $i \in I$ .

Suppose that  $\bar{a}_{i_0}^o \bar{a}_{i_0}^a > 0$  for some index  $i_0 \in I$ . One may then decrease the values of both variables  $\bar{a}_{i_0}^o$  and  $\bar{a}_{i_0}^a$  by the same small positive number. This means, for sufficiently small positive number  $\delta$ , the quadruple  $(\bar{\mathbf{x}}, \bar{\mathbf{a}}^o - \delta \mathbf{e}_{i_0}, \bar{\mathbf{a}}^a - \delta \mathbf{e}_{i_0}, \bar{\mathbf{a}}^r)$  where  $\mathbf{e}_{i_0}$  denotes the unit vector corresponding to index  $i_0$  is feasible for problem (16). Due to the strictly increasing function  $g$ , one gets  $(g(\bar{\mathbf{a}}^r), g(\bar{\mathbf{a}}^a - \delta \mathbf{e}_{i_0}), g(-\bar{\mathbf{a}}^o + \delta \mathbf{e}_{i_0})) <_{\text{lex}} (g(\bar{\mathbf{a}}^r), g(\bar{\mathbf{a}}^a), g(-\bar{\mathbf{a}}^o))$ , which contradicts optimality of  $(\bar{\mathbf{x}}, \bar{\mathbf{a}}^r, \bar{\mathbf{a}}^a, \bar{\mathbf{a}}^o)$  to the problem (16).

Further, suppose that  $(1 - \bar{a}_{i_0}^a) \bar{a}_{i_0}^r > 0$  for some index  $i_0 \in I$ . One may decrease then the value of variable  $\bar{a}_{i_0}^r$  and simultaneously increase  $\bar{a}_{i_0}^a$  by the same small positive number. This means that for sufficiently small positive number  $\delta$  the quadruple  $(\bar{\mathbf{x}}, \bar{\mathbf{a}}^r - \delta \mathbf{e}_{i_0}, \bar{\mathbf{a}}^a + \delta \mathbf{e}_{i_0}, \bar{\mathbf{a}}^o)$  is feasible for problem (16). Hence,  $(g(\bar{\mathbf{a}}^r - \delta \mathbf{e}_{i_0}), g(\bar{\mathbf{a}}^a + \delta \mathbf{e}_{i_0}), g(-\bar{\mathbf{a}}^o)) <_{\text{lex}} (g(\bar{\mathbf{a}}^r), g(\bar{\mathbf{a}}^a), g(-\bar{\mathbf{a}}^o))$ , which contradicts the optimality of  $(\bar{\mathbf{x}}, \bar{\mathbf{a}}^r, \bar{\mathbf{a}}^a, \bar{\mathbf{a}}^o)$  to the problem (16).

Thus  $(\bar{\mathbf{x}}, \bar{\mathbf{a}}^o, \bar{\mathbf{a}}^a, \bar{\mathbf{a}}^r)$  fulfills formula (12) and therefore it is an optimal solution of the corresponding problem (17).

An important advantage of the RPM depends on its easy implementation as an expansion of the original multiple criteria model. Actually, even complicated component achievement functions of the form (7) strictly increase and are concave, thus allowing for implementation of the entire RPM model (2) by an LP expansion (Ogryczak et al. 1992).

The OWA aggregation is obviously a piecewise linear function, since it remains linear within every area of the fixed order of arguments. The ordered achievements used in the OWA aggregation are, in general, difficult to implement due to the pointwise ordering. Its optimization can be implemented using the cumulated ordered achievements  $\bar{\theta}_k(\mathbf{a}) = \sum_{i=1}^k \theta_i(\mathbf{a})$  expressing, respectively: the worst achievement, the total of the two worst achievements, the total of the three worst achievements, etc. Indeed,

$$\sum_{i=1}^m w_i \theta_i(\mathbf{a}) = \sum_{i=1}^m w'_i \bar{\theta}_i(\mathbf{a}) \tag{18}$$

where  $w'_k = w_k - w_{k+1}$  for  $k = 1, \dots, m - 1$  and  $w'_m = w_m$ . This simplifies dramatically the optimization problem since quantities  $\bar{\theta}_k(\mathbf{a})$  can be optimized without use of any integer variables (Ogryczak and Śliwiński 2003). First, let us notice that for any given vector  $\mathbf{a}$ , the cumulated ordered value  $\bar{\theta}_k(\mathbf{a})$  can be found as the optimal value of the following LP problem:

$$\bar{\theta}_k(\mathbf{a}) = \max_{u_{ik}} \left\{ \sum_{i=1}^m a_i u_{ik} : \sum_{i=1}^m u_{ik} = k, 0 \leq u_{ik} \leq 1 \quad \forall i \right\} \tag{19}$$

The above problem is an LP for a given outcome vector  $\mathbf{a}$  while it becomes nonlinear for  $\mathbf{a}$  being a vector of variables. This difficulty can be overcome by taking advantage of the LP dual to (19). Introducing a dual variable  $t_k$  corresponding to the equation  $\sum_{i=1}^m u_{ik} = k$ , and variables  $d_{ik}$  corresponding to the upper bounds on  $u_{ik}$ , one gets the following LP dual of problem (19):

$$\bar{\theta}_k(\mathbf{a}) = \min_{t_k, d_{ik}} \left\{ kt_k + \sum_{i=1}^m d_{ik} : a_i \leq t_k + d_{ik}, d_{ik} \geq 0 \quad \forall i \right\} \tag{20}$$

Due to the duality theory, for any given vector  $\mathbf{a}$ , the cumulated ordered coefficient  $\bar{\theta}_k(\mathbf{a})$  can be found as the optimal value of the above LP problem. It follows from (20) that  $\bar{\theta}_k(\mathbf{a}) = \max \{ kt_k + \sum_{i=1}^m (a_i - t_k)_+ \}$ , where  $(\cdot)_+$  denotes the nonnegative part of a number and  $t_k$  is an auxiliary (unbounded) variable. The latter, with the necessary adaptation to the location problems, is equivalent to the computational formulation of the  $k$ -centrum model



introduced by (Ogryczak and Tamir 2003). Hence, formula (20) provides an alternative proof of that formulation.

Taking advantages of the LP expression (20) for  $\bar{\theta}_k$ , the entire OWA aggregation of the component achievement functions (10) can be expressed in terms of LP. This leads us to the following formulation of the OWA RPM problem (15):

$$\begin{aligned} & \text{lex min} \left[ \sum_{k=1}^m w'_k z'_k, \sum_{k=1}^m w'_k z^a_k, \sum_{k=1}^m w'_k z^o_k \right] \\ & \text{s.t. } \mathbf{x} \in Q \\ & a_i = (f_i(\mathbf{x}) - r_i^r) / (r_i^a - r_i^r), \quad \forall i \in I \\ & a_i - a_i^o + a_i^a + a_i^r = -1, \quad \forall i \in I \\ & a_i^o \geq 0, 0 \leq a_i^a \leq 1, a_i^r \geq 0 \quad \forall i \in I \\ & z_k^r = kt_k^r + \sum_{i=1}^m d_{ik}^r, \quad \forall k \in I \\ & a_i^r \leq t_k^r + d_{ik}^r, d_{ik}^r \geq 0 \quad \forall i, k \in I \\ & z_k^a = kt_k^a + \sum_{i=1}^m d_{ik}^a, \quad \forall k \in I \\ & a_i^a \leq t_k^a + d_{ik}^a, d_{ik}^a \geq 0 \quad \forall i, k \in I \\ & z_k^o = kt_k^o + \sum_{i=1}^m d_{ik}^o, \quad \forall k \in I \\ & -a_i^o \leq t_k^o + d_{ik}^o, d_{ik}^o \geq 0 \quad \forall i, k \in I \end{aligned} \tag{21}$$

Note that the resulting formulation extends the original constraints and criteria with linear inequalities.

**Theorem 7** For any reference levels  $r_i^a > r_i^r$ , any positive strictly decreasing weights  $w_i$ , if  $(\bar{\mathbf{x}}, \bar{\mathbf{a}}^r, \bar{\mathbf{a}}^a, \bar{\mathbf{a}}^o)$  is an optimal solution of the problem (21), then it is an optimal solution of the corresponding problem (13).

*Proof* Let  $(\bar{\mathbf{x}}, \bar{\mathbf{a}}^r, \bar{\mathbf{a}}^a, \bar{\mathbf{a}}^o)$  be an optimal solution of the problem (21) with weight vector  $\mathbf{w}$ . Following the OWA formulas (18) and (20), one may notice that, due to positive and strictly decreasing weights  $w_i$ , the problem (21) is equivalent to the following lexicographic optimization:

$$\text{lex min}_{\mathbf{a} \in A} (A_{\mathbf{w}}(\mathbf{a}^r), A_{\mathbf{w}}(\mathbf{a}^a), A_{\mathbf{w}}(-\mathbf{a}^o))$$

Further, following Lemma 1, due to strict monotonicity of the OWA aggregations with positive weights, the quadruple  $(\bar{\mathbf{x}}, \bar{\mathbf{a}}^r, \bar{\mathbf{a}}^a, \bar{\mathbf{a}}^o)$  is also an optimal solution of the corresponding problem (13).

**Corollary 1** For any reference levels  $r_i^a > r_i^r$ , any positive strictly decreasing weights  $w_i$ , if  $(\bar{\mathbf{a}}^r, \bar{\mathbf{a}}^a, \bar{\mathbf{a}}^o)$  is an optimal solution of the problem (21), then any decision vector  $\bar{\mathbf{x}} \in Q$  generating this solution is an efficient solution of the corresponding MCO problem (1).

**Corollary 2** If  $\bar{\mathbf{x}}$  is an efficient solution of the MCO problem (1), then there exist aspiration levels  $r_i^a = f_i(\bar{\mathbf{x}})$

such that the corresponding triple  $(\bar{\mathbf{a}}^r, \bar{\mathbf{a}}^a, \bar{\mathbf{a}}^o)$  is an optimal solution of the corresponding problem (21), for any reservation levels  $r_i^r < r_i^a$  and any positive strictly decreasing weights  $w_i$ .

### 4 WOWA enhancement

Typical RPM model allows weighting of several achievements only by straightforward rescaling of the achievement values (Ruiz et al. 2009). The OWA RPM model enables one to introduce importance weights to affect achievement importance by rescaling accordingly its measure within the distribution of achievements as defined in the so-called weighted OWA (WOWA) aggregation (Torra 1997; Liu 2006). Let  $\mathbf{w} = (w_1, \dots, w_m)$  and  $\mathbf{p} = (p_1, \dots, p_m)$  be weighting vectors of dimension  $m$  such that  $w_i \geq 0$  and  $p_i \geq 0$  for  $i = 1, 2, \dots, m$  as well as  $\sum_{i=1}^m p_i = 1$  (typically it is also assumed  $\sum_{i=1}^m w_i = 1$ , but it is not necessary in our applications). The corresponding weighted OWA aggregation of outcomes  $\mathbf{a} = (a_1, \dots, a_m)$  is defined as follows (Torra 1997):

$$A_{\mathbf{w}, \mathbf{p}}(\mathbf{a}) = \sum_{i=1}^m \omega_i \theta_i(\mathbf{a}) \tag{22}$$

where the weights  $\omega_i$  are defined as

$$\omega_i = w^* \left( \sum_{k \leq i} p_{\tau(k)} \right) - w^* \left( \sum_{k < i} p_{\tau(k)} \right) \tag{23}$$

with  $w^*$  a monotone increasing function that interpolates points  $(\frac{i}{m}, \sum_{k \leq i} w_k)$  together with the point (0.0) and  $\tau$  representing the ordering permutation for  $\mathbf{a}$  (i.e.  $a_{\tau(i)} = \theta_i(\mathbf{a})$ ). Moreover, function  $w^*$  is required to be a straight line when the point can be interpolated in this way, thus allowing the WOWA to cover the standard weighted mean with weights  $p_i$  as a special case of equal preference weights ( $w_i = 1/m$  for  $i = 1, 2, \dots, m$ ). Actually, for our purpose we use linear interpolation, which obviously satisfies that requirement.

*Example 1* Consider achievements vectors  $\mathbf{a}' = (1, 2)$  and  $\mathbf{a}'' = (2, 1)$ . While introducing preferential weights  $\mathbf{w} = (0.9, 0.1)$ , one may calculate the OWA averages:  $A_{\mathbf{w}}(\mathbf{y}') = A_{\mathbf{w}}(\mathbf{y}'') = 0.9 \cdot 2 + 0.1 \cdot 1 = 1.9$ . Further, let us introduce importance weights  $\mathbf{p} = (0.75, 0.25)$ , which means that results under the first achievement are three times more important than those related to the second criterion. To take into account the importance weights in the WOWA aggregation (22), we introduce piecewise linear function

$$w^*(\xi) = \begin{cases} 0.9\xi/0.5 & \text{for } 0 \leq \xi \leq 0.5 \\ 0.9 + 0.1(\xi - 0.5)/0.5 & \text{for } 0.5 < \xi \leq 1.0 \end{cases}$$

and calculate weights  $\omega_i$  according to the formula (23) as  $w^*$  increments corresponding to importance weights of the ordered outcomes, as illustrated in Fig. 4. In particular, one get  $\omega_1 = w^*(p_2) = 0.45$  and  $\omega_2 = 1 - w^*(p_2) = 0.55$  for vector  $\mathbf{a}'$ , while  $\omega_1 = w^*(p_1) = 0.95$  and  $\omega_2 = 1 - w^*(p_1) = 0.05$  for vector  $\mathbf{a}''$ . Finally,  $A_{w,p}(\mathbf{a}') = 0.45 \cdot 2 + 0.55 \cdot 1 = 1.45$  and  $A_{w,p}(\mathbf{a}'') = 0.95 \cdot 2 + 0.05 \cdot 1 = 1.95$ . Note that one may alternatively compute the WOWA values by using the importance weights to replicate corresponding achievements and calculate then OWA aggregations. In the case of our importance weights  $p = (0.75, 0.25)$  we need to consider three copies of achievement  $a_1$  and one copy of achievement  $a_2$ , thus generating vectors  $\tilde{\mathbf{a}}' = (1, 1, 1, 2)$  and  $\tilde{\mathbf{a}}'' = (2, 2, 2, 1)$  of four equally important achievements. Original preferential weights must be then applied, respectively, to the average of the two smallest outcomes and to the average of two largest outcomes. Indeed, we get  $A_{w,p}(\mathbf{a}') = 0.9 \cdot 1.5 + 0.1 \cdot 1 = 1.45$  and  $A_{w,p}(\mathbf{a}'') = 0.9 \cdot 2 + 0.1 \cdot 1.5 = 1.95$ . We will further formalize this approach and take its advantages to build LP computational models.

The WOWA aggregation may be expressed with an alternative formula using directly preferential weights  $w_i$  as applied to the averages of corresponding portions of the ordered achievements (quantile intervals) according to the

distribution defined by importance weights  $p_i$  (Ogryczak and Śliwiński 2007; Ogryczak and Śliwiński 2007; Ogryczak and Śliwiński 2009):

$$A_{w,p}(\mathbf{a}) = \sum_{i=1}^m w_i m \int_{\frac{i-1}{m}}^{\frac{i}{m}} \bar{F}_{\mathbf{a}}^{(-1)}(\xi) d\xi \tag{24}$$

where  $\bar{F}_{\mathbf{y}}^{(-1)}$  is the stepwise function  $\bar{F}_{\mathbf{y}}^{(-1)}(\xi) = \theta_i(\mathbf{y})$  for  $\beta_{i-1} < \xi \leq \beta_i$ . It can also be mathematically formalized as follows. First, we introduce the left-continuous right tail cumulative distribution function (cdf) defined as:

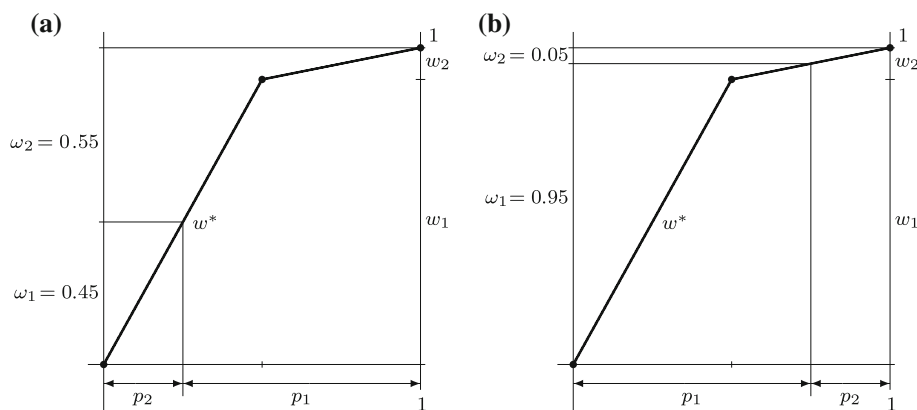
$$\bar{F}_{\mathbf{y}}(d) = \sum_{i \in I} p_i \delta_i(d) \text{ where } \delta_i(d) = \begin{cases} 1 & \text{if } y_i \geq d \\ 0 & \text{otherwise} \end{cases} \tag{25}$$

which for any real (outcome) value  $d$  provides the measure of outcomes greater than or equal to  $d$ . Next, we introduce the quantile function  $\bar{F}_{\mathbf{y}}^{(-1)}$  as the right-continuous inverse of the cumulative distribution function  $\bar{F}_{\mathbf{y}}$ :

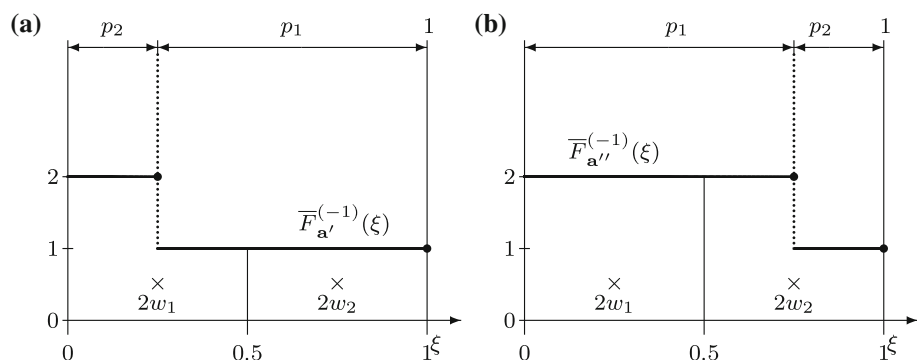
$$\bar{F}_{\mathbf{y}}^{(-1)}(\xi) = \sup\{\eta : \bar{F}_{\mathbf{y}}(\eta) \geq \xi\} \text{ for } 0 < \xi \leq 1.$$

Figure 5 illustrates the application of formula (24) to computations of the WOWA aggregations in Example 1. Note that  $m = 2$ , therefore the area below  $\bar{F}_{\mathbf{a}}^{(-1)}(\xi)$  within interval  $[0, 0.5]$  is multiplied by  $2w_1$  and added to the area below  $\bar{F}_{\mathbf{a}}^{(-1)}(\xi)$  within interval  $[0.5, 1]$  multiplied by  $2w_2$ .

**Fig. 4** Definition of weights  $\omega_i$  for Example 1: (a) vector  $\mathbf{a}' = (1, 2)$ , (b) vector  $\mathbf{a}'' = (2, 1)$



**Fig. 5** Formula (24) applied to calculations in Example 1: (a) vector  $\mathbf{a}' = (1, 2)$ , (b) vector  $\mathbf{a}'' = (2, 1)$



The formula (24) enables an easy proof of the strict monotonicity for the WOWA aggregation defined by positive weights. Indeed, the following assertion is valid.

**Lemma 2** For any positive weights  $\mathbf{w}$  and  $\mathbf{p}$ , the WOWA aggregation  $A_{\mathbf{w},\mathbf{p}}(\mathbf{a})$  is strictly increasing with respect to any component  $a_i$

*Proof* Let  $\mathbf{a}' = \mathbf{a} + \varepsilon \mathbf{e}_{i_0}$  for some  $i_0 \in I$  and  $\varepsilon > 0$ . Then (Ogryczak and Ruszczyński 2002)  $\bar{F}_{\mathbf{a}'}^{(-1)}(\xi) \geq \bar{F}_{\mathbf{a}}^{(-1)}(\xi)$  for any  $0 \leq \xi \leq 1$  and simultaneously  $\int_0^1 \bar{F}_{\mathbf{a}'}^{(-1)}(\xi) d\xi = \sum_{i=1}^m p_i a'_i > \sum_{i=1}^m p_i a_i = \int_0^1 \bar{F}_{\mathbf{a}}^{(-1)}(\xi) d\xi$ . Hence, following the formula (3),  $A_{\mathbf{w},\mathbf{p}}(\mathbf{a}') > A_{\mathbf{w},\mathbf{p}}(\mathbf{a})$ , which completes the proof.

The WOWA-enhanced RPM can be based on the following lexicographic optimization problem (Ogryczak 2008):

$$\text{lex min}_{\mathbf{a} \in A} (A_{\mathbf{w},\mathbf{p}}(\mathbf{a}^r), A_{\mathbf{w},\mathbf{p}}(\mathbf{a}^a), A_{\mathbf{w},\mathbf{p}}(-\mathbf{a}^o)) \tag{26}$$

used to generate current solutions according to the specified preferences. For instance, applying importance weighting  $\mathbf{p} = (\frac{4}{12}, \frac{3}{12}, \frac{2}{12}, \frac{1}{12}, \frac{1}{12}, \frac{1}{12})$  to component achievements together with the OWA weights  $\mathbf{w}$  from Table 4, one gets the WOWA aggregations from Table 5. The corresponding RPM method selects then solution S6, similarly to the case of equal importance weights. On the other hand, when increasing the importance of the last achievement with  $\mathbf{p} = (\frac{1}{12}, \frac{1}{12}, \frac{1}{12}, \frac{1}{12}, \frac{1}{12}, \frac{7}{12})$ , one gets the WOWA values from Table 6 suggesting the selection of solution S7.

The following assertions show that the WOWA RPM problem (26) always generates an efficient solution to the original MCO problem (Theorem 8), thus satisfying the

**Table 5** WOWA RPM selection with importance weights  $\mathbf{p} = (\frac{4}{12}, \frac{3}{12}, \frac{2}{12}, \frac{1}{12}, \frac{1}{12}, \frac{1}{12})$

$\mathbf{w}$	S1	S2	S3	S4	S5	S6	S7
0.5	0.9	0.9	0.9	0.9	0.9	0.9	0.9
	0.9	0.9	0.9	0.9	0.9	0.2	0.9
0.25	0.9	0.9	0.9	0.0	0.0	0.2	0.9
	0.9	0.9	0.9	0.0	0.0	0.2	0.9
0.15	0.0	0.0	0.0	0.0	0.0	0.2	0.9
	0.0	0.0	0.0	0.0	0.0	0.2	0.9
0.05	0.0	0.0	0.0	0.0	0.0	0.2	0.9
	0.0	0.0	0.0	0.0	0.0	0.2	0.9
0.03	0.0	0.0	0.0	0.0	0.0	0.2	0.9
	0.0	0.0	0.0	0.0	0.0	0.2	0.6
0.02	0.0	0.0	0.0	0.0	0.0	0.2	0.2
	0.0	0.0	0.0	0.0	0.0	0.2	0.2
$A_{\mathbf{w},\mathbf{p}}(\mathbf{a}^a)$	0.74	0.68	0.56	0.45	0.45	0.38	0.88

**Table 6** WOWA RPM selection with importance weights  $\mathbf{p} = (\frac{1}{12}, \frac{1}{12}, \frac{1}{12}, \frac{1}{12}, \frac{1}{12}, \frac{7}{12})$

$\mathbf{w}$	S1	S2	S3	S4	S5	S6	S7
0.5	0.9	0.9	0.9	0.9	0.9	0.9	0.9
	0.9	0.9	0.9	0.9	0.9	0.9	0.9
0.25	0.9	0.9	0.9	0.9	0.9	0.9	0.9
	0.9	0.9	0.9	0.9	0.9	0.9	0.6
0.15	0.9	0.9	0.9	0.9	0.9	0.9	0.2
	0.9	0.9	0.9	0.9	0.9	0.9	0.2
0.05	0.9	0.9	0.9	0.9	0.9	0.9	0.2
	0.9	0.9	0.9	0.9	0.9	0.2	0.2
0.03	0.0	0.0	0.0	0.0	0.0	0.2	0.2
	0.0	0.0	0.0	0.0	0.0	0.2	0.2
0.02	0.0	0.0	0.0	0.0	0.0	0.2	0.2
	0.0	0.0	0.0	0.0	0.0	0.2	0.2
$A_{\mathbf{w},\mathbf{p}}(\mathbf{a}^a)$	0.86	0.86	0.86	0.86	0.86	0.85	0.69

property **P1**. Further, following Theorem 9, a solution reaching all the reservation levels is preferred to any solution failing to achieve at least one reservation level and, according to Theorem 10, a solution reaching all the aspiration levels is preferred to any solution failing to achieve at least one aspiration level. Thus, the property **P2** is satisfied in terms of the ARBDS methodology.

**Theorem 8** For any reference levels  $r_i^a > r_i^r$ , any positive weights  $\mathbf{w}$  and  $\mathbf{p}$ , if  $(\bar{\mathbf{a}}^r, \bar{\mathbf{a}}^a, \bar{\mathbf{a}}^o)$  is an optimal solution of the problem (26), then any decision vector  $\bar{\mathbf{x}} \in Q$  generating this solution is an efficient solution of the corresponding MCO problem (1).

*Proof* Let  $\bar{\mathbf{x}}$  be a feasible vector generating  $(\bar{\mathbf{a}}^r, \bar{\mathbf{a}}^a, \bar{\mathbf{a}}^o)$  optimal to the problem (26) with some positive weighting vectors  $\mathbf{w}$  and  $\mathbf{p}$ . Suppose that  $\bar{\mathbf{x}}$  is not efficient to the MCO problem (1). This means, there exists a decision vector  $\mathbf{x} \in Q$  such that  $f_i(\mathbf{x}) \geq f_i(\bar{\mathbf{x}})$  for all  $i \in I$  and  $f_{i_0}(\mathbf{x}) > f_{i_0}(\bar{\mathbf{x}})$  for some outcome index  $i_0 \in I$ . Let us define  $a_i^r, a_i^a$  and  $a_i^o$  according to the formula (12). The triple  $(\mathbf{a}^r, \mathbf{a}^a, \mathbf{a}^o)$  is then a feasible solution of the problem (26). Moreover,  $a_i^r \leq \bar{a}_i^r, a_i^a \leq \bar{a}_i^a$  and  $a_i^o \geq \bar{a}_i^o$  for all  $i \in I$  where at least one of strict inequalities  $a_{i_0}^r < \bar{a}_{i_0}^r$  or  $a_{i_0}^a < \bar{a}_{i_0}^a$  or  $a_{i_0}^o > \bar{a}_{i_0}^o$  holds. Hence, due to strict monotonicity of the WOWA aggregation with positive weighting vectors, one gets  $A_{\mathbf{w},\mathbf{p}}(\mathbf{a}^r) \leq A_{\mathbf{w},\mathbf{p}}(\bar{\mathbf{a}}^r), A_{\mathbf{w},\mathbf{p}}(\mathbf{a}^a) \leq A_{\mathbf{w},\mathbf{p}}(\bar{\mathbf{a}}^a)$  and  $A_{\mathbf{w},\mathbf{p}}(-\mathbf{a}^o) \leq A_{\mathbf{w},\mathbf{p}}(-\bar{\mathbf{a}}^o)$  with at least one inequality strict. The latest assertion contradicts the lexicographic optimality of  $(\bar{\mathbf{a}}^r, \bar{\mathbf{a}}^a, \bar{\mathbf{a}}^o)$  for the problem (26), which completes the proof.

**Theorem 9** For any reference levels  $r_i^a > r_i^r$ , any positive weights  $\mathbf{w}$  and  $\mathbf{p}$ , if  $(\bar{\mathbf{a}}^r, \bar{\mathbf{a}}^a, \bar{\mathbf{a}}^o)$  is an optimal solution of

the problem (26), then all the reservation level underachievements  $\bar{a}_i^r$  are equal 0 whenever there exists a feasible solution  $\mathbf{x} \in Q$  such that  $f_i(\mathbf{x}) \geq r_i^r$  for all  $i \in I$ .

*Proof* Let  $(\bar{\mathbf{a}}^r, \bar{\mathbf{a}}^a, \bar{\mathbf{a}}^o)$  be an optimal solution of the problem (26) with some positive weighting vectors  $\mathbf{w}$  and  $\mathbf{p}$ . Suppose that  $\bar{a}_{i_0}^r < 0$  for some  $i_0 \in I$  and there exists a feasible solution  $\mathbf{x} \in Q$  such that  $f_i(\mathbf{x}) \geq r_i^r$  for all  $i \in I$ . Let us define  $a_i^r, a_i^a$  and  $a_i^o$  according to the formula (12) and note that  $a_i^r = 0$  for all  $i \in I$ . The triple  $(\mathbf{a}^r, \mathbf{a}^a, \mathbf{a}^o)$  is then a feasible solution of the problem (26) and, due to positive weights,  $A_{\mathbf{w}, \mathbf{p}}(\mathbf{a}^r) = 0 < A_{\mathbf{w}, \mathbf{p}}(\bar{\mathbf{a}}^r)$  thus contradicting the lexicographic optimality of  $(\bar{\mathbf{a}}^r, \bar{\mathbf{a}}^a, \bar{\mathbf{a}}^o)$ .

**Theorem 10** For any reference levels  $r_i^a > r_i^r$ , any positive weights  $\mathbf{w}$  and  $\mathbf{p}$ , if  $(\bar{\mathbf{a}}^r, \bar{\mathbf{a}}^a, \bar{\mathbf{a}}^o)$  is an optimal solution of the problem (26), then all the aspiration level underachievements  $\bar{a}_i^a$  are equal to 0 whenever there exists a feasible solution  $\mathbf{x} \in Q$  such that  $f_i(\mathbf{x}) \geq r_i^a$  for all  $i \in I$ .

*Proof* Let  $(\bar{\mathbf{a}}^r, \bar{\mathbf{a}}^a, \bar{\mathbf{a}}^o)$  be an optimal solution of the problem (26) with some positive weighting vectors  $\mathbf{w}$  and  $\mathbf{p}$ . Suppose that  $\bar{a}_{i_0}^a < 0$  for some  $i_0 \in I$  and there exists a feasible solution  $\mathbf{x} \in Q$  such that  $f_i(\mathbf{x}) \geq r_i^a$  for all  $i \in I$ . Let us define  $a_i^r, a_i^a$  and  $a_i^o$  according to the formula (12) and note that  $a_i^a = a_i^r = 0$  for all  $i \in I$ . The triple  $(\mathbf{a}^r, \mathbf{a}^a, \mathbf{a}^o)$  is then a feasible solution to the problem (26) and, due to positive weights,  $A_{\mathbf{w}, \mathbf{p}}(\mathbf{a}^a) = 0 < A_{\mathbf{w}, \mathbf{p}}(\bar{\mathbf{a}}^a)$ , thus contradicting the lexicographic optimality of  $(\bar{\mathbf{a}}^r, \bar{\mathbf{a}}^a, \bar{\mathbf{a}}^o)$ .

In order to show that the WOWA RPM model (26) provides us with a complete parameterization of the efficient set, we will prove in the following theorem that for each efficient solution  $\bar{\mathbf{x}}$  there exist aspiration and reservation vectors for which  $\bar{\mathbf{x}}$  with the corresponding values of the multilevel achievements is an optimal solution of the problem (26).

**Theorem 11** If  $\bar{\mathbf{x}}$  is an efficient solution of the MCO problem (1), then there exist aspirations levels  $r_i^a$  such that the corresponding triple  $(\bar{\mathbf{a}}^r, \bar{\mathbf{a}}^a, \bar{\mathbf{a}}^o)$  is an optimal solution to the problem (26), for any reservation levels  $r_i^r < r_i^a$  and positive weighting vectors  $\mathbf{w}$  and  $\mathbf{p}$ .

*Proof* Let us set the aspiration levels as  $r_i^a = f_i(\bar{\mathbf{x}})$  for  $i \in I$ . For any reservation levels  $r_i^r < r_i^a$ , all the corresponding multilevel achievements defined according to the formula (12) take zero values:  $\bar{\mathbf{a}}^r = 0, \bar{\mathbf{a}}^a = 0$  and  $\bar{\mathbf{a}}^o = 0$ . Suppose that for some weights the triple  $(0, 0, 0)$  is not an optimal solution of the corresponding problem (26). This means that there exists a vector  $\mathbf{x} \in Q$  such that  $\mathbf{a}^r = 0,$

$\mathbf{a}^a = 0, \mathbf{a}^o \geq 0$  and  $A_{\mathbf{w}, \mathbf{p}}(-\mathbf{a}^o) < A_{\mathbf{w}, \mathbf{p}}(-\bar{\mathbf{a}}^o)$ . Hence,  $f_i(\mathbf{x}) \geq f_i(\bar{\mathbf{x}}) \quad \forall i \in I$  and  $f_{i_0}(\mathbf{x}) > f_{i_0}(\bar{\mathbf{x}})$  for some index  $i_0 \in I$ . The latest assertion contradicts the efficiency of  $\bar{\mathbf{x}}$  in (1), which completes the proof.

In the proof of Theorem 11, we have used one set of preferential parameters leading to the given efficient solution. Obviously, there are many alternative settings of the parameters allowing to reach this goal. For instance, one may set the reservation levels as  $r_i^r = f_i(\bar{\mathbf{x}})$  for  $i \in I$  while taking any aspiration levels  $r_i^a > r_i^r$ .

According to the original definition, the WOWA operator is a quite complicated function of the aggregated outcomes. Nevertheless, similar to the OWA RPM model (21), the WOWA RPM optimization can be simply implemented as an LP expansion of the original MCO problem. Recall that the formula (24) defines the WOWA operator applying the preferential weights  $w_i$  to importance weighted averages within quantile intervals. It may be reformulated using the tail averages (Ogryczak and Śliwiński 2007a, b, 2009):

$$A_{\mathbf{w}, \mathbf{p}}(\mathbf{a}) = \sum_{k=1}^m w'_k m L\left(\mathbf{a}, \mathbf{p}, \frac{k}{m}\right) \tag{27}$$

where weights  $w'_k = w_k - w_{k+1}$  for  $k = 1, \dots, m - 1$  and  $w'_m = w_m$ , and  $L(\mathbf{y}, \mathbf{p}, \xi)$  is defined by left-tail integrating of  $\bar{F}_{\mathbf{y}}^{(-1)}$ , i.e.,

$$L(\mathbf{y}, \mathbf{p}, \xi) = \int_0^\xi \bar{F}_{\mathbf{y}}^{(-1)}(\alpha) d\alpha \tag{28}$$

Values  $L(\mathbf{a}, \mathbf{p}, \xi)$  for any  $0 \leq \xi \leq 1$  can be given by optimization:

$$L(\mathbf{a}, \mathbf{p}, \xi) = \max_{\pi_i} \left\{ \sum_{i=1}^m a_i \pi_i : \sum_{i=1}^m \pi_i = \xi, 0 \leq \pi_i \leq p_i \quad \forall i \in I \right\} \tag{29}$$

Introducing a dual variable  $t$  corresponding to the equation  $\sum_{i=1}^m \pi_i = \xi$ , and variables  $d_i$  corresponding to the upper bounds on  $\pi_i$ , one gets the following LP dual expression for  $L(\mathbf{a}, \mathbf{p}, \xi)$

$$L(\mathbf{a}, \mathbf{p}, \xi) = \min_{t, d_i} \left\{ \xi t + \sum_{i=1}^m p_i d_i : t + d_i \geq a_i, d_i \geq 0 \quad \forall i \in I \right\} \tag{30}$$

According to (27) and (30), one gets finally the following model for the WOWA RPM:

$$\begin{aligned}
 & \text{lex min} \left[ \sum_{k=1}^m w'_k z'_k, \sum_{k=1}^m w'_k z''_k, \sum_{k=1}^m w'_k z''_k \right] \\
 & \text{s.t. } \mathbf{x} \in Q \\
 & a_i = (f_i(\mathbf{x}) - r_i^r) / (r_i^a - r_i^r), \quad \forall i \in I \\
 & a_i - a_i^o + a_i^a + a_i^r = -1, \quad \forall i \in I \\
 & a_i^o \geq 0, 0 \leq a_i^a \leq 1, a_i^r \geq 0 \quad \forall i \in I \\
 & z'_k = kt'_k + m \sum_{i=1}^m p_i d'_{ik}, \quad \forall k \in I \\
 & a'_i \leq t'_k + d'_{ik}, d'_{ik} \geq 0 \quad \forall i, k \in I \\
 & z''_k = kt''_k + m \sum_{i=1}^m p_i d''_{ik}, \quad \forall k \in I \\
 & a''_i \leq t''_k + d''_{ik}, d''_{ik} \geq 0 \quad \forall i, k \in I \\
 & z''_k = kt''_k + m \sum_{i=1}^m p_i d''_{ik}, \quad \forall k \in I \\
 & -a''_i \leq t''_k + d''_{ik}, d''_{ik} \geq 0 \quad \forall i, k \in I
 \end{aligned} \tag{31}$$

thus allowing for implementation as an LP expansion of the original problem. The following theorem justifies the model (31) as an implementation of the WOWA RPM approach (26), thus preserving its preference model properties.

**Theorem 12** *For any reference levels  $r_i^a > r_i^r$ , any positive importance weights  $p_i$  and positive strictly decreasing weights  $w_i$ , if  $(\bar{\mathbf{x}}, \bar{\mathbf{a}}^r, \bar{\mathbf{a}}^a, \bar{\mathbf{a}}^o)$  is an optimal solution of the problem (31), then it is an optimal solution of the corresponding problem (26).*

*Proof* Let  $(\bar{\mathbf{x}}, \bar{\mathbf{a}}^r, \bar{\mathbf{a}}^a, \bar{\mathbf{a}}^o)$  be an optimal solution of the problem (31) with some positive weighting vectors  $\mathbf{w}$  and  $\mathbf{p}$ . Following the WOWA formulas (27) and (30), one may notice that the problem (31) is equivalent to the following lexicographic optimization:

$$\text{lex min}_{\mathbf{a} \in A} (A_{\mathbf{w}, \mathbf{p}}(\mathbf{a}^r), A_{\mathbf{w}, \mathbf{p}}(\mathbf{a}^a), A_{\mathbf{w}, \mathbf{p}}(-\mathbf{a}^o))$$

Further, following Lemmas 1 and 2, the quadruple  $(\bar{\mathbf{x}}, \bar{\mathbf{a}}^r, \bar{\mathbf{a}}^a, \bar{\mathbf{a}}^o)$  is also an optimal solution of the corresponding problem (26).

**Corollary 3** *For any reference levels  $r_i^a > r_i^r$ , any positive importance weights  $p_i$  and positive strictly decreasing preferential weights  $w_i$ , if  $(\bar{\mathbf{a}}^r, \bar{\mathbf{a}}^a, \bar{\mathbf{a}}^o)$  is an optimal solution of the problem (31), then any decision vector  $\bar{\mathbf{x}} \in Q$  generating this solution is an efficient solution of the corresponding MCO problem (1).*

**Corollary 4** *If  $\bar{\mathbf{x}}$  is an efficient solution of the MCO problem (1), then there exist aspirations levels  $r_i^a = f_i(\bar{\mathbf{x}})$  such that the corresponding triple  $(\bar{\mathbf{a}}^r, \bar{\mathbf{a}}^a, \bar{\mathbf{a}}^o)$  is an optimal solution of the corresponding problem (31), for any reservation levels  $r_i^r < r_i^a$ , any positive importance weights  $p_i$  and positive strictly decreasing preferential weights  $w_i$ .*

### 5 Illustrative example

In order to illustrate the WOWA RPM performances let us analyze a simplified multicriteria problem of information system selection. We consider a billing system selection for a telecommunication company. The decision is based on six criteria related to the system reliability, processing efficiency, investment costs, installation time, operational costs and warranty period. All these attributes may be viewed as criteria, either maximized or minimized. Table 7 presents all the criteria with their measurement units and optimization directions. The aspiration and reservation levels for each criterion as well as the importance factors (not normalized to weights  $p_i$ ) are also specified for several achievements. The importance factors emphasize achievements related to the quality of the system. Five candidate billing systems have been accepted for the final selection procedure. They all met the minimal requirements defined by the reservation levels. Table 8 presents for all the systems (columns) their criteria values  $y_i$  and the corresponding linear achievement values  $a_i$  computed according to the formula (11). Exactly, the formula (11) is directly applied to the maximized outcomes, while its symmetric adaptation is applied to the minimized ones.

Table 9 presents for all the systems (columns) their aspiration underachievements values  $\mathbf{a}^a$  ordered from the

**Table 7** Criteria and their attributes for the sample billing system selection

	$f_1$ Reliability	$f_2$ Efficiency	$f_3$ Investment cost	$f_4$ Installation time	$f_5$ Operational cost	$f_6$ Warranty period
Units	1–10	CAPS	mln. EUR	months	mln. EUR	years
Optimization	Max	Max	Min	Min	Min	Max
Reservation	8	50	2	12	1.25	0.5
Aspiration	10	200	0	6	0.5	2
Importance weights	3	3	1	1	1	3



**Table 8** Criteria values  $y_i$  and individual achievements  $a_i$  for five billing systems

$i$	System A		System B		System C		System D		System E	
	$y_i$	$a_i$	$y_i$	$a_i$	$y_i$	$a_i$	$y_i$	$a_i$	$y_i$	$a_i$
1	10	1.00	9	0.50	10	1.00	9	0.50	10	1.00
2	200	1.00	100	0.33	170	0.80	90	0.27	150	0.67
3	1	0.50	0.3	0.85	0.8	0.60	0.2	0.90	0.5	0.75
4	8	0.67	3	1.50	8	0.67	8	0.67	5	1.20
5	1	0.33	1	0.33	0.6	0.87	0.2	1.40	1	0.33
6	2	1.00	2	1.00	1	0.33	2	1.00	1.5	0.67

**Table 9** WOWA RPM selection with criteria importance factors (3, 3, 1, 1, 1, 3)

$w$	A	B	C	D	E
0.6	0.67	0.67	0.67	0.73	0.67
	0.50	0.67	0.67	0.73	0.33
0.2	0.33	0.67	0.67	0.73	0.33
	0.00	0.67	0.40	0.50	0.33
0.1	0.00	0.50	0.33	0.50	0.33
	0.00	0.50	0.30	0.50	0.33
0.05	0.00	0.50	0.30	0.33	0.33
	0.00	0.15	0.30	0.10	0.25
0.03	0.00	0.00	0.13	0.00	0.00
	0.00	0.00	0.00	0.00	0.00
0.02	0.00	0.00	0.00	0.00	0.00
	0.00	0.00	0.00	0.00	0.00
$A_{w,p}(a^a)$	0.414	0.602	0.556	0.622	0.455

worst to the best, taking into account replications according to the importance weights allowing for easy WOWA aggregation computations following the formula (24). One may notice that except for system D, all the other systems have the same worst achievement value  $\max_i a_i^a = 0.67$ . Selection among systems A, B, C and E depends only on the regularization of achievements aggregation used in the RPM approach. The WOWA RPM method taking into account the importance weights together with the preferential weights  $w = (0.6, 0.2, 0.1, 0.05, 0.03, 0.02)$  points out that system A is the best one.

System A, similar to B and D, is characterized by the highest operational cost. In order to improve the operational cost one may try to strengthen the requirements given by the corresponding reference levels. Let us take  $r_5^a = 0.2$  and  $r_5^j = 1.0$ . Still there are no positive reservation underachievements and the selection is based on the aspiration underachievements. Table 10 presents for all the systems their aspiration underachievements values ordered from the worst to the best with replications according to the importance weights of the WOWA formula (24). One may

**Table 10** WOWA RPM selection with criteria importance factors (3, 3, 1, 1, 1, 3) and modified reference levels

$w$	A	B	C	D	E
0.6	1.00	1.00	0.67	0.73	1.00
	0.50	0.67	0.67	0.73	0.33
0.2	0.33	0.67	0.67	0.73	0.33
	0.00	0.67	0.50	0.50	0.33
0.1	0.00	0.50	0.40	0.50	0.33
	0.00	0.50	0.33	0.50	0.33
0.05	0.00	0.50	0.30	0.33	0.33
	0.00	0.15	0.30	0.10	0.25
0.03	0.00	0.00	0.30	0.00	0.00
	0.00	0.00	0.00	0.00	0.00
0.02	0.00	0.00	0.00	0.00	0.00
	0.00	0.00	0.00	0.00	0.00
$A_{w,p}(a^a)$	0.483	0.612	0.630	0.622	0.465

notice that now system E is pointed out as the best, meeting the requirements, actually not much better than system A. Both these systems have the worst value of the operational cost. Systems C and D characterized by lower (better) values of the operational cost are evaluated as much worse. Indeed, to increase the importance of the operational cost criterion, we should rather increase its importance weight. For instance, when instead of changing the reference levels, we increase the importance of criterion  $f_5$  to 3 and simultaneously decrease the importance of criterion  $f_6$  to 1, we get the results presented in Table 11. System C with relatively low (but not the lowest) operational cost is then pointed out as the best one.

On the other hand, when we increase strongly the importance of criterion  $f_5$  to 5 and simultaneously decrease the importance of criteria  $f_1$  and  $f_2$  to 1 while leaving the importance of  $f_6$  on the level 3, we get the results presented in Table 12. System D with the lowest operational cost is then selected.

In order to provide a lucid illustration, we have considered an example of discrete choice problem with a few explicitly given alternatives where any complicated aggregation method can be applied. However, the WOWA RPM model enables one to solve MCO problems with infinite number of decision alternatives implicitly given by constraints of the feasible set.

### 6 Conclusions

The reference point method is a very convenient technique for interactive analysis of the multiple criteria optimization problems. It provides the DM with a tool for an open analysis of the efficient frontier. The interactive analysis is

**Table 11** WOWA RPM selection with criteria importance factors (3, 3, 1, 1, 3, 1)

w	A	B	C	D	E
0.6	0.67	0.67	0.67	0.73	0.67
	0.67	0.67	0.40	0.73	0.67
0.2	0.67	0.67	0.33	0.73	0.67
	0.50	0.67	0.20	0.50	0.33
0.1	0.33	0.67	0.20	0.50	0.33
	0.00	0.67	0.20	0.50	0.33
0.05	0.00	0.50	0.13	0.33	0.33
	0.00	0.50	0.13	0.10	0.25
0.03	0.00	0.50	0.13	0.00	0.00
	0.00	0.15	0.00	0.00	0.00
0.02	0.00	0.00	0.00	0.00	0.00
	0.00	0.00	0.00	0.00	0.00
$A_{w,p}(a^a)$	0.536	0.636	0.401	0.622	0.550

**Table 12** WOWA RPM selection with criteria importance factors (1, 1, 1, 1, 5, 3)

w	A	B	C	D	E
0.6	0.67	0.67	0.67	0.73	0.67
	0.67	0.67	0.67	0.50	0.67
0.2	0.67	0.67	0.67	0.33	0.67
	0.67	0.67	0.40	0.10	0.67
0.1	0.67	0.67	0.33	0.00	0.67
	0.50	0.67	0.20	0.00	0.33
0.05	0.33	0.50	0.13	0.00	0.33
	0.00	0.15	0.13	0.00	0.33
0.03	0.00	0.00	0.13	0.00	0.33
	0.00	0.00	0.13	0.00	0.25
0.02	0.00	0.00	0.13	0.00	0.00
	0.00	0.00	0.00	0.00	0.00
$A_{w,p}(a^a)$	0.603	0.619	0.546	0.412	0.611

navigated with the commonly accepted control parameters expressing reference levels for the individual objective functions. The component achievement functions quantify the DM satisfaction from the individual outcomes with respect to the given reference levels. The final scalarizing function is built as the augmented max–min aggregation of component achievements, which means that the worst individual achievement is essentially maximized, but the optimization process is additionally regularized with the term representing the average achievement. The regularization by the average achievement is easily implementable, but it may disturb the basic max–min aggregation. In order to avoid inconsistencies caused by the regularization, the max–min solution may be regularized by taking into account also the second worst achievement, the third worse

and so on, thus resulting in much better modeling of the reference levels concept (Kostreva et al. 2004).

The OWA aggregation with monotonic weights combines all the component achievements allocating the largest weight to the worst achievement, the second largest weight to the second worst achievement, the third largest weight to the third worst achievement, and so on. Further, following the concept of Weighted OWA (Torra 1997), the importance weighting of several achievements may be incorporated into the RPM. Such a WOWA enhancement of the RPM uses importance weights to affect achievement importance by rescaling accordingly its measure within the distribution of achievements rather than straightforward rescaling of achievement values (Ruiz et al. 2009). The ordered regularizations are more complicated in implementation due to the requirement of pointwise ordering of component achievements. However, the recent progress in optimization methods for ordered averages (Ogryczak and Śliwiński 2003) allows one to implement the OWA RPM quite effectively by taking advantages of piecewise linear expression of the cumulated ordered achievements. A similar computational model can be achieved for the WOWA RPM. Actually, the resulting formulation extends the original constraints and criteria with simple linear inequalities, thus allowing for a quite efficient implementation.

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